Tiger 320 Series PROGRAMMING CODE SHEET

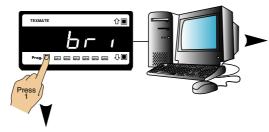
Contents

Initial Setup Procedures
Tiger 320 Series Code Logic Diagram4
CALIBRATION MODE5
CODE 1
CODE 2
CODES 3 to 5
CODES 6 to 9
CODE 10
SETPOINT PROGRAMMING MODE - SPC_1 to SPC_6 .11
Detailed Descriptions of Setpoint Functions14
Customer Code Settings – Main Programming Mode 15
Customer Code Settings – Setpoint Programming Mode18
Commonly Used Registers19
User Notes



Programming Tips

- Use the P button to step through the codes of the Main or Setpoint Programming Mode.
- To save a Main Programming Mode code setting and return directly to the operational display, press the P button and then the P and ♠ buttons at the same time.
- To save a **Setpoint** Programming Mode setting and return directly to the operational display, press the P button and then the P and ▼ buttons at the same time.
- 4) When configuring the three-digit code and setpoint settings, pressing the ♠ and ▶ buttons at the same time increases the displayed parameter in increments of 100 counts.



Front panel programming

This programming code sheet (PCS) is a quick reference document that allows you to quickly view the meter's programming codes.

When you become familiar with the meter and the programming code structure, the PCS can be used in place of the user manual.



Note:

All displays shown in this code sheet are for a 5-digit, 7-segment LED display. Other Tiger 320 Series displays will be slightly different.

To configure the meter's programming codes from the front panel, the meter uses the three right-hand side display digits. These are known as the 1st, 2nd, and 3rd digits and can be seen in the diagram below.

Operational Display



The logic diagram on Page 4 shows the code structure of the Tiger 320 Series meter range. Also, the difference between the E and T version of the Tiger range is described. The diagrams on the following pages show the three-digit settings available for each code.

Programming via PC

Meter configuration utility program

With a serial output module installed, the meter can be fully configured through the meter configuration utility program. In addition to all application function settings, the configuration program also provides access to added features such as:

- · Code blanking.
- Display text editing.
- · Configuration data copying.
- · Downloading macros to the meter.

Code blanking

Code blanking blanks out all function codes not required by the application. This means that specific procedures such as recalibration and setpoint reprogramming can be achieved in a few simple steps from the front panel buttons.

To turn code blanking and macro settings OFF, carry out the Code Blanking and Macro Check on Page 3.

Display text editing

This function allows displayed text, such as setpoint titles, to be edited to suit your applications.

For example, a setpoint could be edited to read [TNKLo] for tank level low, or [brKoF] for brake off.

Configuration data copying

This function allows the current meter configuration settings to be copied and saved for later referral or for restoration.

Macros

Texmate has a growing library of macros to suit a wide range of standard customer applications. Macros can be installed in the meter, via the compiler or configuration program, and run automatically when the meter is powered up.

Tamper-proof settings

All Tiger 320 Series meters have tamper-proof lockout switches to prevent users' configuration settings from being inadvertently changed.

Code blanking is also used (via the PC) to blank out codes not used, making them operator tamper-proof, but leaving selected codes open for operator adjustment.



Note:

3-digit programming codes are specified within square brackets [XXX].

If an X appears in the description of a 3-digit programming code or in a configuration procedure, this means that more than one choice can be made, or any number displayed in that digit is not relevant to the function being explained.



Initial Setup Procedures

Before configuring the meter, carry out the following meter configuration checks:

- · Model and software code version check.
- · Code blanking and macro check.

After powering-up the meter, check the model and software code version number and note this below.

Model No:
Software Version No:
Customer ID:
Macro ID:

Model and Software Code Version Check

The meter model and software code version number can be checked at any time while in the operational display using the following procedure.



Programming Tip

The Model and Software Code Version checking procedure can be performed at any time without interfering with other configuration settings.



MODEL & SOFTWARE CODE VERSION CHECK

Step 1

Press and hold the ♠ and ♣ buttons

Step 2



Operational Display

While holding both buttons, press the Prog. button then release all three buttons



Step 3

The above displays toggles three times before returning to the operational display



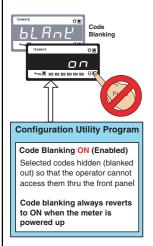


Operational Display

Code Blanking and Macro Check

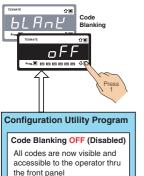
Code Blanking

Tiger 320 Series controllers have the ability to hide (blank out) all or some programming codes to prevent tampering through the front panel. This function is known as code blanking and is ideal for preventing settings, such as calibration, being changed by the operator.



The code blanking function can be either enabled (set to ON) or disabled (set to OFF) through the front panel. Changing which codes are visible, and therefore accessible to the operator, can only be done through the Configuration Utility program.

During power-up, the code blanking function always reverts to ON (enabled). This means that when the meter is switched ON all codes are visible except those that have been blanked out during meter configuration.



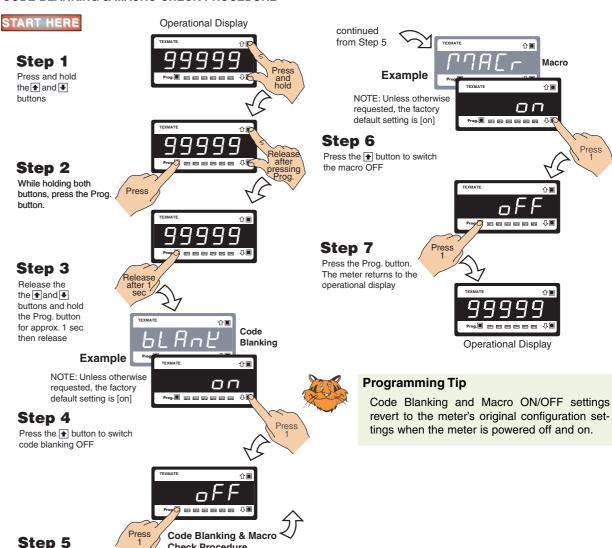
Code blanking can be set to OFF (disabled) by the operator by following the Code Blanking and Macro Check procedure opposite. Setting code blanking to OFF means that all codes are visible to the operator and can be tampered with.

Macros

A macro is a set of commands that run automatically when the controller is powered up. Macros can be installed in the controller at the factory during initial programming or by the customer at some later date. Macros are written and compiled using the Tiger Development System (TDS) compiler program and loaded into the controller using either the TDS or the configuration program.

Turning the macro OFF means that the controller will not perform the automatic commands pre-programmed to run with the macro. Unless otherwise requested. Texmate program the controller in the code blanking and macro ON (enabled) setting. Texmate has a growing library of macros to suit a wide range of standard customer applications.

CODE BLANKING & MACRO CHECK PROCEDURE



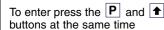
Check Procedure

(Step 6)

continued on next page

Press the Prog. button.

Tiger 320 Series Code Logic Diagram





To enter press the P and • buttons at the same time

Main Programming Mode



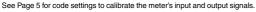
Display Brightness



Allows you to adjust the display brightness in a range of 8 settings. 0 being dull. 7 being bright.

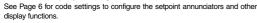


Calibration Modes for Input and Output





Code 1 - Display Configuration





Code 2 - CH1 Measurement Task & Sampling Rate

See Page 7 for code settings to configure the CH1 measurement task and sam-



Code 3 - CH1 Post Processing & Serial Mode Functions



See Page 8 for code settings to configure CH1 post processing and serial



Code 4 – CH2 Measurement Task & 32-point Linearization

See Page 8 for code settings to configure the second channel (CH2) measurement task and 32-point linearization settings when using dual input signal



Р

Code 5 - CH3 Functions

See Page 8 for code settings to configure the third channel (CH3) when using triple input signal conditioners



Code 6 – CH4 Functions



See Page 9 for code settings to configure the fourth channel (CH4) when using quad input signal conditioners.



Code 7 - Result Processing



See Page 9 for code settings to configure the meter for processing the result of CH1 and CH2.



Code 8 - Data Logging & Print Mode



See Page 9 for code settings to configure data logging and data printing using the meter.



Code 9 – Functions for Digital Input Pins



See Page 9 for code settings to configure the meter for inputs from external sources through the digital input pins.

[Cod10]

Code 10 - Bargraph Setup



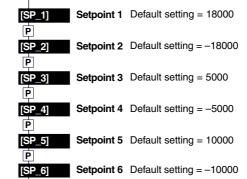
See Page 10 for code settings to configure the meter's bargraph display.



Setpoint Programming Mode

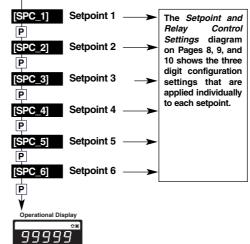
Setpoint Activation Values Mode

Enter these menus to set setpoint (SP) activation values



Setpoint & Relay Control Settings Mode

Enter these menus to configure SP control settings



E/T Versions of Tiger 320 Series Programmable Meter Controller

Tiger 320 Series Programmable Meter Controllers (PMCs) come in two versions: the economy E version, or the top-of-the-line T version.

The standard E version comes with 4 kilobits of EEPROM installed, whereas the standard T version comes with 32 kilobits of EEPROM Installed, Also, the T version can have a macro installed.

The standard 4-kilobit E version can be upgraded to 32 or 512 kilobits. The standard 32-kilobit T version can be upgraded to 512 kilobits. The amount of EEPROM installed in the controller determines the range of functions it is capable of performing. The following table lists the functions that require specific amounts of memory.

Version	rsion Memory Fun (kilobits)		Remarks
Е	4 (standard)	1 linearization table	Table 1 is available to be applied to channels 1 to 4 and result.
	32	4 linearization tables	Tables 1 to 4 are available to be applied to channels 1 and 2 and result.
			Table 3 can be applied to channel 3.
			Table 4 can be applied to channel 4.
			All four tables can be cascaded to form a single 125-point linearization table available to be applied to channels 1 and 2 and result.
	512	Data logging	With 512 kilobits installed, the controller can perform data logging functions along with complete linearization functionality. With a real-time clock installed, date and time stamps can be included.
Т	32 (standard)	4 linearization tables	As for E version with 32 kilobits installed.
		Macro programming	A macro can be programmed to suit a user's logic control application.
	512	Data logging	As for E version with 512 kilobits installed, but with macro programming functionality available.

Only available with selected input modules.

Note 7:

4 4

4

4

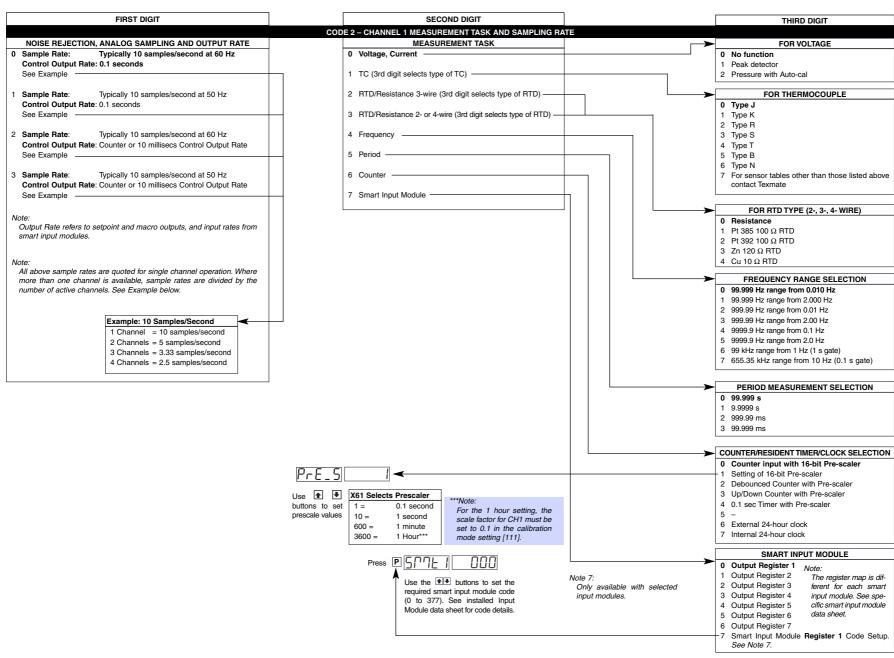
5

4

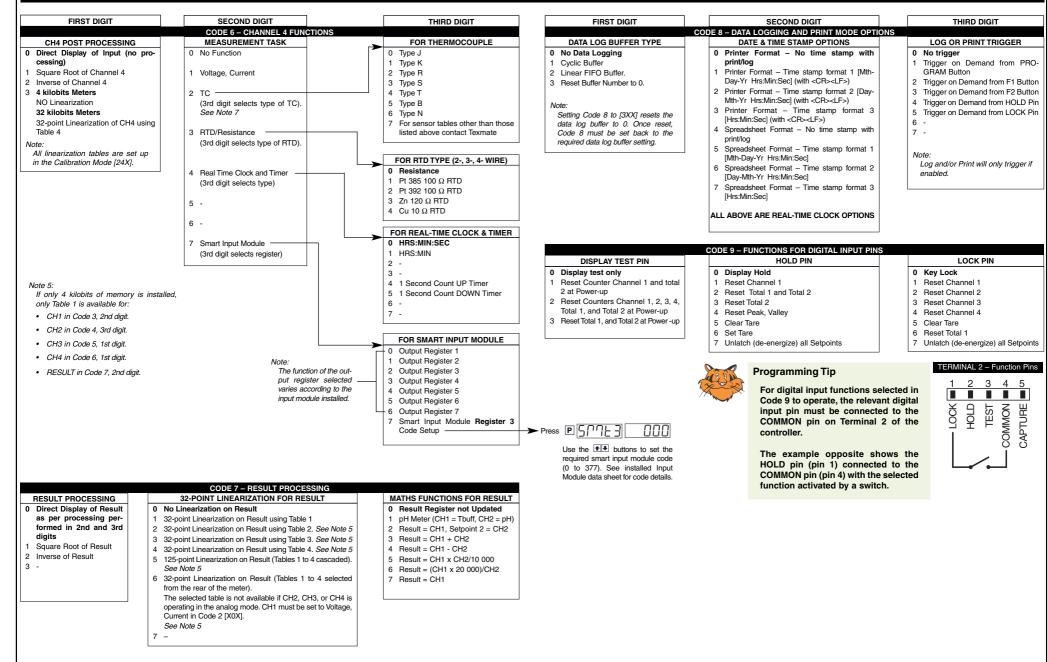
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CODE 2



CODES 6 to 9



CODE 10

Code 10 is only available with Note: Data source for the bargraph is set bargraph versions of the meter up in Code 1 [X51]. Set Up Scaling for Linear Bargraph FIRST DIGIT SECOND DIGIT THIRD DIGIT CODE 10 - BARGRAPH SETUP BARGRAPH DISPLAY SETTINGS BARGRAPH DISPLAY FORMAT BARGRAPH TYPE Bar Low Bar High • Bar Nominal 0 No Function 0 Setpoints on Bar 0 Linear 3X0 @ 6Ar 0 🗈 6Ar _ 0 P 68r_n 1 Via linearization Table 1 1 Peak, Valley on Bar 1 Disable Overrange Flashing 2 -1 + 3 -3X i H9999 49999 2 Set up Colors 4 Min/Max with setpoints (low end of bar = VALLEY, high end of bar = PEAK) 3 Log - 10 Bar/Decade 3 Set up Bar Scaling 5 -4 Log - 20 Bar/Decade Bar Nominal 6 -5 Log - 25 Bar/Decade Bar Nominal sets the point on the bargraph at which the bar For example, if the meter's full scale range is 20,000 counts, the 7 Bar Only (no setpoints on the bar) 6 Log - 33 Bar/Decade midpoint is 10,000 counts. If a signal of 10,000 counts is begins to light up. This can be any position between and includ-7 Log - 50 Bar/Decade applied, only one segment at the 10,000 count mark lights up. ing the bar low and bar high settings. If a signal of 17,000 counts is applied, the segments between If bar nominal is set to the bar low setting, the bargraph the center segment (10,000 counts) and the 17,000 count mark behaves like a typical bargraph making the segments light up light up. from the **bottom** of the bar and grow towards the top. If a signal of 5000 counts is applied, the segments between If bar nominal is set to the bar high setting, this makes all seg-Set Up Bargraph Colors the center segment (10,000 counts) and the 5000 count ments from the displayed signal to the top of the bar light up. mark light up. The bargraph colors are not applied to specific setpoints. They 2XX 🗈 Colr oFF As the signal increases, the number of lit segments between are applied to whichever setpoint is configured at the lowest the signal and the bar high setting becomes steadily less. When 1 setting and then to each next highest setpoint in turn. the signal reaches the bar high setting no segments are lit. □ [colr2] An added feature of this bargraph is that it can also be nonrEd If all six setpoints are used the colors are set as follows: Setting bar nominal to the midpoint between bar low and bar symetrical. This means that the bar nominal setting does not high makes the bargraph behave like a typical center zero bar-□ [alr 3 need to be set at the mid-point between bar low and bar high. 1 Color BELOW lowest setpoint graph. This means the bargraph lights up at the center of the For example, if the bargraph is configured to display -200 to This is the bargraph color before it reaches ManGE bar and moves either up or down the bar depending on the dis-800 °C, bar low is set to -200 counts and bar high is set to 800 a setnoint played signal. counts. Bar nominal is set to 0 counts. If a signal of -50 °C is 1 Color 2 Color ABOVE lowest setpoint applied, the bar lights from 0 down to -50. If a signal of 600 °C Color ABOVE next highest setpoint Color 3 is applied, the bar lights from 0 up to 600. Color 4 Color ABOVE next highest setpoint P Colca Color 5 Color ABOVE next highest setpoint Pressing the Color 6 Color ABOVE next highest setpoint buttons at the same Set Up Scaling for Logirithmic Bargraph Color 7 Color ABOVE highest setpoint time returns to [oFF] + OrnGE Reference 1 **Bar Nominal 1** • Example of Bars per Decade ■ b8c _ n OR 1 • 3X4 49999 OrnGE OR • 3X5 Logirithmic Bargraph Scaling oFF 80 dBm 1.000.000 40 dBm 100,000 30 dBm In all logirithmic scales a reference level is OR 70 dBm required that is the level at 0 dB. 10,000 20 dRm For example, in an RF measurement 0 dBm is at OR 60 dBm 100.000 -30 dRn a reference of 1 mW. The scale is calculated from: 50 dRm 10,000 20 dBm 1000 -10 dRn counts (input)

Reference. This is the number of counts displayed for a 0 dB reference.

1

1

49999

Bar Nominal. See Bar Nominal description

10
$$\log_{10} \frac{\text{counts (input)}}{\text{reference}}$$

If the meter is scaled so that:

1 mW = 100 counts and 1 W = 100,000 counts

Then the reference for 0 dBm would be set to 100 counts

$$10 \log_{10} \frac{(\text{input})}{100} = 0 \text{ dBm}$$

Now every 10 dBm represents a decade, the bargraph can be scaled to a different amount of bars per decade (as set in the 3rd digit).

See Example of Bars per Decade diagram opposite.

Decade (Counts)	dBm
1	-20
10	-10
100	0
1000	10
10,000	20
100,000	30
1,000,000	40

2 February, 2005 Prog. Code Sheet V3.08a (NZ101)

1 000 000 -

100.000 -

10 000 -

1000 -

10 Bars/Decade

40 dBm

30 dRm

20 dBm

10 dBm

10,000

1000

20 dBm

10 dBm

20 Bars/Decade

1000

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50 Bars/Decade

33 Bars/Decade

10 dBm

1000

10 dBm

25 Bars/Decade

SETPOINT PROGRAMMING MODE – SPC_1 to SPC_6

Setpoint Setup Sequence

► Follow These Steps

The following procedures are written for SP1, all other setpoints are configured in a similar manner.

 Press the P and I buttons at the same time. This enters the setpoint programming mode. The display toggles between [SP_1] and [18000].

This is SP1 of the **Setpoint Activation Values Mode**. Use the \P and \P buttons to set SP1 or the \P button to move to the required setpoint.

 After all required setpoint activation values have been set, press the button until [SPC_1] appears. This is the Setpoint & Relay Control Settings Mode.

SPC_1 is the **setpoint and relay control settings** programming menu for SP1. Set the three digits according to the codes in the *Setpoint and Relay Control Function Settings* opposite in the following order:

Third Digit - Setpoint Delay Mode

Set to [XX5] and program the hysteresis, deviation, or PID functions as required for SP1.

Reset back to [XX0].

Third Digit - Setpoint Timer Mode

Set to [XX6] and program the timer mode functions as required for SP1.

Reset back to [XX0].

Third Digit - Setpoint Reset & Trigger Functions

Set to [XX7] and program the reset and trigger functions as required for SP1.

Reset back to [XX0]

Second Digit - Setpoint Activation Source Mode

Set to [X1X] to select the setpoint activation source for SP1 from any channel or selected register shown above. Reset back to [X0X].

If the SP source is from an external digital input, set to one of either [X2X] to [X7X] to select the setpoint activation source from one of six digital inputs (2 to 7). See *Note at 2nd digit.

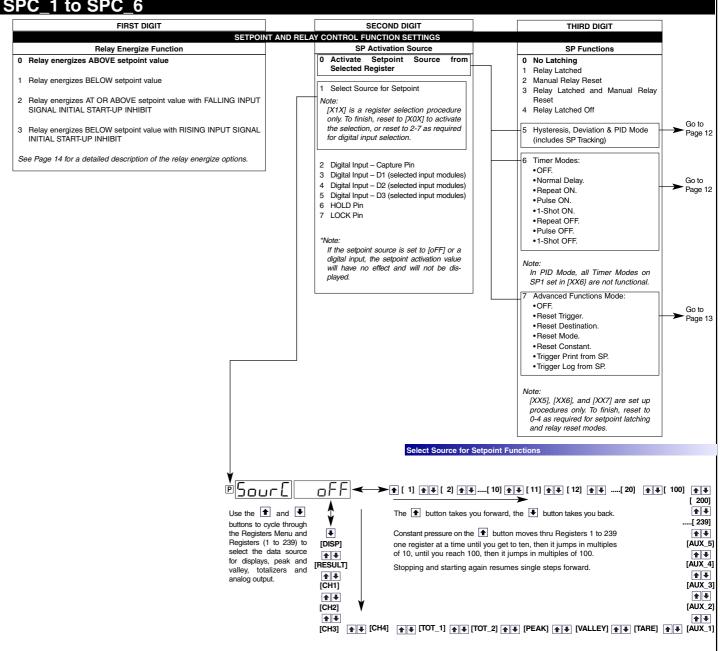
First Digit - Relay Energize Mode

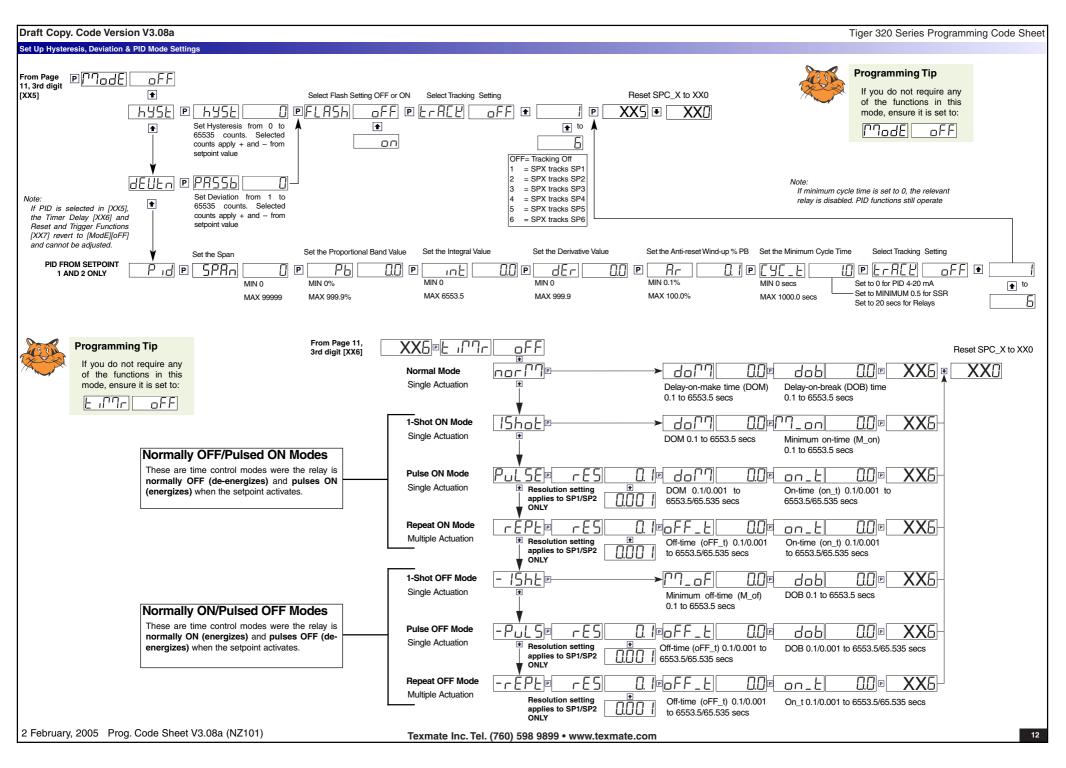
Select the relay energize mode for SP1 from 0 to 3.

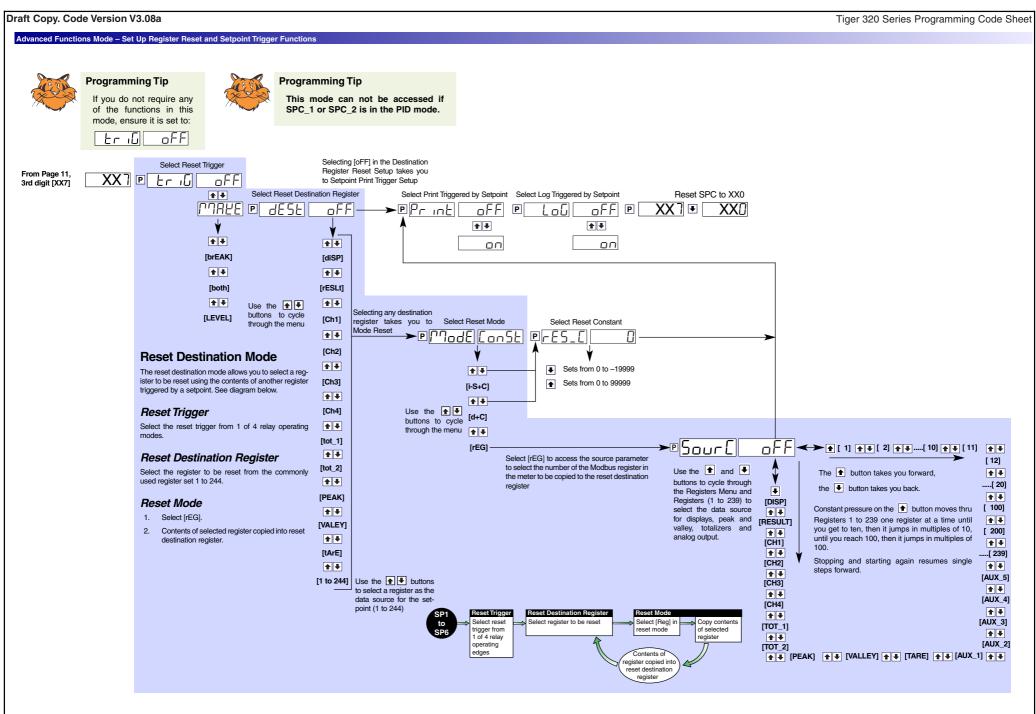
Third Digit - Relay Latching & Manual Reset Functions

Program the third digit setpoint relay latching and manual reset functions between 0 to 4 as required.

- 3) Press the P button to move to move to [SPC 2].
- 4) Repeat Step 2 for all required setpoints.







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Tiger 320 Series Programming Code Sheet

Detailed Descriptions of Setpoint Functions

1st Digit in Setpoint Programming Mode

Following is a detailed description of the options available on the 1st digit of the setpoint programming mode [SPC] settings listed on Page 11.

FIRST DIGIT

Relay Energize Function

0 Energizes ABOVE setpoint value

HYSTERESIS selected – relay energizes AT OR ABOVE setpoint value plus hysteresis counts. De-energizes BELOW setpoint value minus hysteresis counts.

Note

If hysteresis set with ZERO counts, relay energizes AT OR ABOVE the setpoint value.

DEVIATION selected – relay energizes INSIDE deviation band (setpoint ± deviation counts). De-energizes OUTSIDE deviation band (setpoint ± deviation counts). **PID selected** – controls ABOVE setpoint value.

1 Energizes BELOW setpoint value

HYSTERESIS selected – relay energizes BELOW setpoint value minus hysteresis counts. De-energizes AT OR ABOVE setpoint value plus hysteresis counts.

Note:

If hysteresis set with ZERO counts, relay energizes BELOW the setpoint value.

DEVIATION selected – relay energized OUTSIDE deviation band (setpoint ± deviation counts). De-energized INSIDE deviation band (setpoint ± deviation counts). **PID selected** – controls BELOW setpoint value.

2 Energizes AT OR ABOVE setpoint value with FALLING INPUT SIGNAL INITIAL START-UP INHIBIT

HYSTERESIS selected – relay energizes AT OR ABOVE setpoint value plus hysteresis counts with FALLING INPUT SIGNAL INITIAL START-UP INHIBIT. De-energizes BELOW setpoint value minus hysteresis counts with FALLING INPUT SIGNAL INITIAL START-UP INHIBIT.

Note:

If hysteresis set with ZERO counts, relay energizes AT OR ABOVE the setpoint value.

DEVIATION selected – relay energizes INSIDE deviation band (setpoint ± deviation counts) with FALLING INPUT SIGNAL INITIAL START-UP INHIBIT. De-energizes OUT-SIDE deviation band (setpoint ± deviation counts) with FALLING INPUT SIGNAL INITIAL START-UP INHIBIT.

PID selected - controls ABOVE setpoint value.

3 Energizes BELOW setpoint value with RISING INPUT SIGNAL INITIAL START-UP INHIBIT

HYSTERESIS selected – relay energizes BELOW setpoint value plus hysteresis counts with RISING INPUT SIGNAL INITIAL START-UP INHIBIT. De-energizes BELOW setpoint value minus hysteresis counts with RISING INPUT SIGNAL INITIAL START-UP INHIBIT

Note:

If hysteresis set with ZERO counts, relay energizes BELOW the setpoint value.

DEVIATION selected – relay energizes OUTSIDE deviation band (setpoint ± deviation counts) with RISING INPUT SIGNAL INITIAL START-UP INHIBIT. De-energizes INSIDE deviation band (setpoint ± deviation counts) with RISING INPUT SIGNAL INITIAL START-UP INHIBIT.

PID selected - controls BELOW setpoint value.

Explanation Of Setpoint Trigger and Reset Functions

The setpoint trigger and reset functions are available on all 6 setpoints. The various parameters of these functions are described as follows.

Trigger Type

The trigger parameter gives the option of selecting which edge of the relay operation the reset function, print function, and data logging function should activate on. It can be set to either:

- Off Disables all trigger functions
- Make operates on the make edge only.
- Break operates on the break edge only.
- Both operates on both make and break edges.
- Level operates after every sample period if relay is ON.

Reset Destination

The reset destination parameter defines the target register in the meter that is to be modified in some way when the reset trigger conditions for this relay are met. Any Modbus register number from 1 to 255 can be selected as a reset destination. If the [DEST] parameter is set to [OFF], the reset function is disabled and the Reset Mode and Reset Constant/Source selection are not displayed during setup. The setup sequence jumps straight to the Print parameter.

Reset Mode

The reset mode parameter defines what type of reset effect is required. The following different options are available.

Const – This mode stores a user defined constant into the selected destination register. In most cases this number will be zero but it can be any number.

I-S+C – This mode stores the current input value **I**, defined by the setpoint source, minus the setpoint value **S** plus a user defined constant **C**. It would normally be used with a counting or totalizing application where the amount of setpoint overshoot needs to be retained after the reset function. The constant value would normally be zero but could be used to provide an offset if required.

D+C – This mode adds the user defined constant **C** to the current value in the selected reset destination register **D**. It can be used to increment or decrement a register by any amount.

Reg – This mode copies the contents of a user selectable register into the reset destination register (see Reset Constant to select the source register).

It can be used to capture data on an event and store it in an unused channel for display or analog output, etc.

Reset Constant

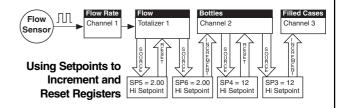
This parameter defines the constant value to be used in the Const, I-S+C, D+C modes as previously explained. Its default value is zero. This parameter is not available if Reg is selected as the reset mode.

Source (only available in Reg mode)

If the reset mode is set to **Reg** then the source parameter allows you to select the number of the Modbus register in the meter to be copied to the reset destination register.

Resetting and Incrementing Using Setpoints

Setpoints may be used to reset and/or increment registers. In the example shown opposite, 2 liter soft drink bottles are being filled and packed 12 to a case. Using the setpoint reset and increment feature, the number of bottles and the total number of filled cases is easily calculated and displayed. Totalizer 1 counts from 0 to 2, resets, and repeats. CH2 counts from 0 to 12, resets, and repeats.



Customer Code Settings – Main Programming Mode

CALIBRA	TION MODE	[CAL]				
1st DIGIT	2nd DIGIT	3rd DIGIT	SUB-SETTINGS	1st DIGIT 2nd DIGIT	3rd DIGIT	SUB-SETTINGS
ON DEMA	AND FUNCTIONS			CALIBRATION PROCED	URES	
		RESULT	010 020 SPAN INPUT 030 ZERO INPUT SPAN INPUT 040 CHANNEL 050 CHANNEL	Manual Calibration		100 OFFSET SCALE 101 OFFSET SCALE 102 OFFSET SCALE 103 OFFSET SCALE 104 OFFSET SCALE
		CH1	011 021 SPAN INPUT 031 ZERO INPUT SPAN INPUT 041 CHANNEL 051 CHANNEL	Two-point Calibration		110 ZERO INPUT SPAN INPUT 111 ZERO INPUT SPAN INPUT 112 ZERO INPUT SPAN INPUT 113 ZERO INPUT SPAN INPUT 114 ZERO INPUT SPAN INPUT
		CH2	012 022 SPAN INPUT 032 ZERO INPUT SPAN INPUT 042 CHANNEL 052 CHANNEL	Calibrate Thermocouple		121 ZERO INPUT 32°F SPAN INPUT 2500°F 122 ZERO INPUT 32°F SPAN INPUT 2500°F 123 ZERO INPUT 32°F SPAN INPUT 2500°F 151 CAL LOW OUTPUT CAL HIGH OUTPUT 152 CAL LOW OUTPUT CAL HIGH OUTPUT
		СН3	013 023 SPAN INPUT 033 ZERO INPUT SPAN INPUT 043 CHANNEL 053 CHANNEL			ISZ CAL LOW COTPOT CAL HIGH COTPOT
		CH4	014 024 SPAN INPUT 034 ZERO INPUT SPAN INPUT 044 CHANNEL 054 CHANNEL			

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CALIBRATION MODE [CAL] Continued		
1st DIGIT 2nd DIGIT 3rd DIGIT SUB-SETTINGS		
RELATED CALIBRATION FUNCTIONS	'	
Serial Output		
200 BAUD PARITY	ADDRESS TIME DELAY	
201 BAUD PARITY	ADDRESS TIME DELAY	
202 BAUD PARITY	ADDRESS TIME DELAY	
203 BAUD PARITY	ADDRESS TIME DELAY	
204 BAUD PARITY	ADDRESS TIME DELAY	
Auto Toro Maintenana		
Auto Zero Maintenance 210 AZ CAPTURE AZ	MOTION AZ APERTURE	
	MOTION AZ APERTURE	
<u></u>	MOTION AZ APERTURE	
l	MOTION AZ APERTURE	
214 AZ CAPTURE AZ	MOTION AZ APERTURE	
Averaging Samples & Averaging Window 220 AVERAGE SAMPLES	AVERAGE WINDOW	
221 AVERAGE SAMPLES	AVERAGE WINDOW	
222 AVERAGE SAMPLES	AVERAGE WINDOW	
223 AVERAGE SAMPLES	AVERAGE WINDOW	
224 AVERAGE SAMPLES	AVERAGE WINDOW	
K Factor & Totalizer Cutoff		
231 SCALE FACTOR	CUTOFF	
232 SCALE FACTOR	CUTOFF	
32-point Linearization Tables		
240 MODE		
241 MODE		
242 MODE		
243 MODE		
244 MODE		
Scale Analog Output		
251 ZERO FULL SC	ILE .	
252 ZERO FULL SC	ALE	

)E 1				CODE 2				CODE 10					
DIGIT	2nd DIGIT	3rd DIGIT	SUB-SETTINGS	1st DIGIT	2nd DIGIT	3rd DIGIT	PRESCALER	1st DIGIT	2nd DIGIT	3rd DIGIT			
_											SCALING FOR LINEAU		
_			X50 SOURCE	CODE 3					PH COLORS		3X0 BAR LOW	BAR HIGH	BAR NOMINAL
_			X51 SOURCE	1st DIGIT	2nd DIGIT	3rd DIGIT		2XX COI			3X1 BAR LOW	BAR HIGH	BAR NOMINAL
_			X52 SOURCE						OR 2		SCALING FOR LOGIR	THMIC BARGRAPH	
			X53 SOURCE	CODE 4				COI	OR 3		3X3 REFERENCE	BAR NOMINAL	
			X54 SOURCE	1st DIGIT	2nd DIGIT	3rd DIGIT	PRESCALER	COI	LOR 4		3X4 REFERENCE	BAR NOMINAL	
			X55 SOURCE					COI	OR 5		3X5 REFERENCE	BAR NOMINAL	
			X56 SOURCE	CODE 5				COI	OR 6		3X6 REFERENCE	BAR NOMINAL	
			X57 SOURCE	1st DIGIT	2nd DIGIT	3rd DIGIT	SMART INPUT MODULE SETTINGS	COI	LOR 7		3X7 REFERENCE	BAR NOMINAL	
			X60 DISPLAY										
			X61 DISPLAY										
			X62 DISPLAY	CODE 6									
			X63 DISPLAY	1st DIGIT	2nd DIGIT	3rd DIGIT	SMART INPUT MODULE SETTINGS						
			X64 DISPLAY				SETTINGS						
			X65 DISPLAY	0005.7									
			X66 DISPLAY	1st DIGIT	2nd DIGIT	3rd DIGIT							
			X67 DISPLAY	ISI DIGIT	Zila Digit	3rd Digit							
			X70 CHARACTER										
			X71 CHARACTER	CODE 8									
			X72 CHARACTER	1st DIGIT	2nd DIGIT	3rd DIGIT							
			X73 CHARACTER										
1			X74 CHARACTER	CODE 9									
1			X75 CHARACTER	1st DIGIT	2nd DIGIT	3rd DIGIT							
_]			X76 CHARACTER										
_			X77 CHARACTER										

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Tiger 320 Series Programming Code Sheet

Customer Code Settings – Setpoint Programming Mode

SP ACTIVATION VALUES						
SETPOINT	VALUE					
SP1						
SP2						
SP3						
SP4						
SP5						
SP6						

SETPOINT & RELAY CONTROL SETTINGS MODE SPC_1 TO SPC_6

SELECT DATA SOURCE	DELAY MODE SETTINGS		
SPC_1 _ 1 _	SPC_1 5 HYSTERESIS	ANNUNCIATOR FLASHING	SP TRACKING
SPC_2 _ 1 _	SPC_2 5 HYSTERESIS	ANNUNCIATOR FLASHING	SP TRACKING
SPC_3 _ 1 _	SPC_3 5 HYSTERESIS	ANNUNCIATOR FLASHING	SP TRACKING
SPC_4 _ 1 _	SPC_4 5 HYSTERESIS	ANNUNCIATOR FLASHING	SP TRACKING
SPC_5 _ 1 _	SPC_5 HYSTERESIS	ANNUNCIATOR FLASHING	SP TRACKING
SPC_6 _ 1 _	SPC_65 HYSTERESIS	ANNUNCIATOR FLASHING	SP TRACKING

DEVIATION	ANNUNCIATOR FLASHING	SP TRACKING
DEVIATION	ANNUNCIATOR FLASHING	SP TRACKING
DEVIATION	ANNUNCIATOR FLASHING	SP TRACKING
DEVIATION	ANNUNCIATOR FLASHING	SP TRACKING
DEVIATION	ANNUNCIATOR FLASHING	SP TRACKING
DEVIATION	ANNUNCIATOR FLASHING	SP TRACKING

SETPOINT FINAL SETTINGS

	1st DIGIT	2nd DIGIT	3rd DIGIT
SPC_1			
SPC_2			
SPC_3			
SPC_4			
SPC_5			
SPC_6			

PID CONTROL SETTINGS						
SPC_1 5 SPAN	PB	INT	DER	ARW	мст	SP TRACKING
SPC_2 5 SPAN	PB	INT	DER	ARW	мст	SP TRACKING
SPC_3 5 SPAN	PB	INT	DER	ARW	МСТ	SP TRACKING
SPC_4 5 SPAN	PB	INT	DER	ARW	МСТ	SP TRACKING
SPC_5 5 SPAN	РВ	INT	DER	ARW	мст	SP TRACKING
SPC_6 5 SPAN	РВ	INT	DER	ARW	мст	SP TRACKING

	TIMER MODE SETTINGS												
	ODO OFTTINO		NORMALLY OFF / PULSED ON MODES					NORMALLY ON / PULSED OFF MODES					
	SPC SETTING	NORMAL	REPEA	T ON	PULSE ON		1-SHOT ON	1-SHOT OFF	PULSE OFF		REPEAT OFF		
J													
	SPC_1 6	DOM	Resolution	OFF T	Resolution	DOM	DOM	M OFF	Resolution	OFF T	Resolution	OFF T	
		DOB		ONT		ON_T	M ON	DOB		DOB		ONT	
	SPC_2 6	ром	Resolution	OFF T	Resolution	DOM	DOM	M OFF	Resolution	OFF T	Resolution	OFF T	
		DOB		ONT		ONT	M ON	DOB		DOB		ONT	
				T	- -					T	<u> </u>	II	
	SPC_36	DOM	Resolution	OFF T	Resolution	DOM	DOM	M OFF	Resolution	OFFT	Resolution	OFFT	
		DOB		ONT		ONT	M ON	DOB		DOB		ON T	
	SPC_46	ром	Resolution	OFF T	Resolution	DOM	DOM	M OFF	Resolution	OFF T	Resolution	OFF T	
		DOB		ONT		ONT	M ON	DOB		DOB		ONT	
	000 5	DOM .	B t. et	Torr T	Bernstein	Tpour I	DOM:	III OFF	D tur	Torr T	Bernstein	Torral	
	SPC_56	ром	Resolution	OFFT	Resolution	DOM	DOM	M OFF	Resolution	OFFT	Resolution	OFFT	
		DOB		ONT		ONT	M ON	DOB		DOB		ON T	
	SPC 6 6	ром	Resolution	OFF T	Resolution	ром	ром	M OFF	Resolution	OFFT	Resolution	OFF T	
	0	$= \pm \pm$	i leaoiulloii		nesolution		=		Hesolution	=	nesolution		
		DOB		ONT		ONT	M ON	DOB		DOB		ONT	

REGISTER RESET & TRIGGER FUNCTIONS SETTINGS									
SPC_1 7 [triG]	[dESt]	[ModE]	[rES_C]	[SourC]	[Print]	[LoG]			
SPC_2 7 [triG]	[dESt]	[ModE]	[rES_C]	[SourC]	[Print]	[LoG]			
SPC_3 7 [triG]	[dESt]	[ModE]	[rES_C]	[SourC]	[Print]	[LoG]			
SPC_4 7 [triG]	[dESt]	[ModE]	[rES_C]	[SourC]	[Print]	[LoG]			
SPC_5 7 [triG]	[dESt]	[ModE]	[rES_C]	[SourC]	[Print]	[LoG]			
SPC_67 [triG]	[dESt]	[ModE]	[rES_C]	[SourC]	[Print]	[LoG]			

Commonly Used Registers

A Tiger 320 Series controller has 6,144 registers available for use by the meter's operating system and the Tiger Macro Development System (TDS).

See TDS Macro Tutorial (NZ212) for further information on developing macros for Tiger 320 Series controllers.

40 Manually Selectable Registers

Using the front panel buttons, there are 40 registers that may be selected for use within the following functions:

- [CODE_1] Display Configuration [X50]. Select a register as the data source for displays, peak and valley, totalizers and analog outputs.
- Setpoint Control Settings [X1X]. Select a register as the data source for a setpoint.
- Setpoint Control Settings [XX7]. Select a destination register that is reset by a setpoint with the contents of a selected source register.
- Setpoint Control Settings [XX7]. Select the contents of one register to be copied into another register by a setpoint.

The 40 registers that can be selected as a data source, a reset source, or a reset destination for the above functions are shown in the table opposite.

This table shows, in seven columns, the functions where these registers can be used.

Where a register is more likely to be used in a particular function, a closed circle ● is shown in the column. For those functions where a register is less likely to be used, an open circle ○ is shown.

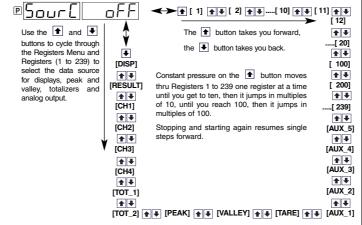
No register number is shown in the table for the first 11 functions as these are identified on the display menu for direct selection by their function names.

Beginning at [OFF] on the display, when selecting a register as the data source, reset, or destination for a function, pressing the • button takes you through the numerical register list beginning at register [1] and proceeding to register [239] and then the named registers. Pressing the • button takes you in the reverse order starting at register [DISP] and ending at register [1].

To cycle through the numerical register list quickly, keep constant pressure on the ▶ button. This increments one register at a time until you reach register [10] then jumps

in increment blocks of 10 until you reach [100]. If you keep pressure on the button you jump from register [100] to [200] and then stop cycling. If the register you require is between [100] and [200] then stop pressing the button at [100]. Resume pressing the button again and the process is repeated, incrementing one register at a time until [10] and then incrementing in multiples of 10 until you reach [200]. Repeat this process for a number between [200] and [239].

Press the ● and ● buttons at the same time to take you directly back to [OFF].



Registers that Should Not be Used

The following registers are contained within the selectable Register Set, but they should not be selected because they are either reserved for future use, or for use by the operating system only:

15, 38, 47, 48, 52, 53, 61-64, 123-128, 140, 141, 234-244

Selection of any of these registers may cause a malfunction.



Note:

3-digit programming codes are specified within square brackets [XXX]. If an X appears in the description of a 3-digit programming code or in a configuration procedure, this means that more than one choice can be made, or any number displayed in that digit is not relevant to the function being explained.

Register Functions	Register Numbers	Data Source for Displays	Data Source for Peak & Valley	Data Source for Analog Outputs 1 & 2	Data Source for Totalizers 1 & 2	Data Source for Setpoints	Reset Source	Reset Dest.
Display [diSP]	-		•	•	•	•		
Result [rESLt]	-	•	•	•	•	•	•	•
CH1 [Ch1]	-	•	•	•	•	•	•	•
CH2 [Ch2]	-	•	•	•	•	•	•	•
CH3 [Ch3]	-	•	•	•	•	•	•	•
CH4 [Ch4]	-	•	•	•	•	•	•	•
Total 1 [tot_1]	-	•	•	•		•	•	•
Total 2 [tot_2]	-	•	•	•		•	•	•
Peak [PEAK]	-	0				•	0	•
Valley [VALEY]	-	0				•	0	•
Tare [tArE]	-	0	0	0		0	0	•
PID Output 1	50	0	0	0		0		
PID Output 2	51	0	0	0		0		
Smart Result 1	54	0	0	0				0
Smart Result 2	55	0	0	0				0
Smart Result 3	56	0	0	0				0
Smart Result 4	57	0	0	0				0
Smart Result 5	58							0
Smart Result 6	59							0
Smart Result 7	60	_				_	_	0
Analog Output 1	83	0				0	0	0
Analog Output 2	84	0				0	0	0
Timer 1	95	0				0	0	0
Timer 2	96	0				0	0	0
Smart Reset Offset 1	121							•
Smart Reset Offset 2								•
Clock - Seconds Clock - Minutes	213 214					0		
Clock - Minutes	214							
	216							
Clock - Days Clock - Date	217							
Clock - Date Clock - Month	217							
Clock - World	219							
Setpoint Latch	221							
Relay De-energize	222							•
Zero Offset - Result						0		
Zero Offset - CH1	228					0		
Zero Offset - CH2	229					0		
Zero Offset - CH3	230					0		
Zero Offset - CH4	231					o		

User Notes

Thermocouple Calibration for CH1

STEP_1

Select K Type Thermocouple for Initial Calibration

Enter Code 2 and select K type thermocouple for initial calibration.



STEP 2

Thermocouple Initial Calibration

Enter the Calibration mode [CAL], set to [121] and press the P button twice to carry out the thermocouple initial calibration procedure.



STEP 3

Select Temperature Units

Enter the Calibration mode [CAL], set to [101].



procedure opposite.

If you want °F set offset to 0 and scale factor to 1.

If you want °C set offset to 0.5555 and scale factor to -178.

Note, once the temperature units have been selected, the temperature inputs to the meter must be in the same units.

STEP 4

Select Thermocouple Type

Re-enter Code 2 and select the required thermocouple type, noise rejection setting, and the analog sampling and output rate.



Select noise rejection, analog sampling & output rate: Select thermocouple type:

STEP 5

Fine Tune Calibration over Specific Temperature Range

Enter the Calibration mode [CAL], set to [111] and fine tune the thermocouple calibration over the required temperature range.



Note, this is not a mandatory step. Carry out only if required.

Follow Steps 1 to 4 for setting channels 2 and 3, using the following settings:

CH2: Code 4 [11X] for K type, CAL [122] to calibrate K type, Code 4 [1X0]

to select specific TC, CAL [112] to trim selected TC.

CH3: Code 5 [X21] for K type, CAL [123] to calibrate K type, Code 5 [X2X] to select specific TC, CAL [113] to trim selected TC.

For a detailed thermocouple calibration procedure, see Advanced Calibration & On Demand Mode Supplement (NZ203).

2 February, 2005 Prog. Code Sheet V3.08a (NZ101)

CH1 Initial RTD Calibration

STEP 1

Select Type Pt 385 100 Ω RTD

Enter Code 2 and select type Pt 385 100 Ω RTD for initial calibration.



STEP 2

RTD Initial Calibration

Enter the Calibration mode [CAL], set to [131] and press the P button once to carry out the RTD initial calibration procedure.



STEP 3

Select Temperature Units

Enter the Calibration mode [CAL], set to [101]. If you want °F set offset to 0.0 and scale fac- See Converting °F to °C



tor to 1.0000. If you want °C set offset to 0.5555 and scale

Note, once the temperature units have been selected, the temperature inputs to the meter must be in the same units.

STEP 4

Select RTD Type

factor to -178.

Re-enter Code 2 and select the required RTD type, noise rejection setting, and the analog sampling and output rate.



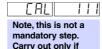
Select RTD type:

STEP 5

CH3:

Calibration Trim

Enter the Calibration mode [CAL], set to [111] and fine tune the RTD calibration over the required temperature range.



required.

Follow Steps 1 to 4 for setting channels 2 and 3, using the following settings:

CH2: Code 4 [210] for type 385, CAL [132] to calibrate type 385, Code 4 [2X0] to select specific RTD. CAL [112] to fine tune selected RTD.

Code 5 [X31] for type 385, CAL [133] to calibrate type 385, Code 5

[X3X] to select specific RTD, CAL [113] to fine tune selected RTD. CH4:

Code 6 [X31] for type 385, CAL [134] to calibrate type 385, Code 6 [X3X] to select specific RTD, CAL [113] to fine tune selected RTD.

For a detailed RTD calibration procedure, see Advanced Calibration & On Demand Mode Supplement (NZ203).

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Converting °F to °C

- 1) Calibrate the meter to suit the temperature sensor input. Use K type thermocouple input for thermocouples. Use RTD 385 for RTDs.
- 2) To convert °F to °C enter the calibration mode and set [CAL] to [10X].
- Set the offset [OFFS_R] to [-178] counts on the display.
- 4) Set the scale factor [SCAL_R] to [0.55555] on the display.

Ignore the decimal point on OFFSET settings

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