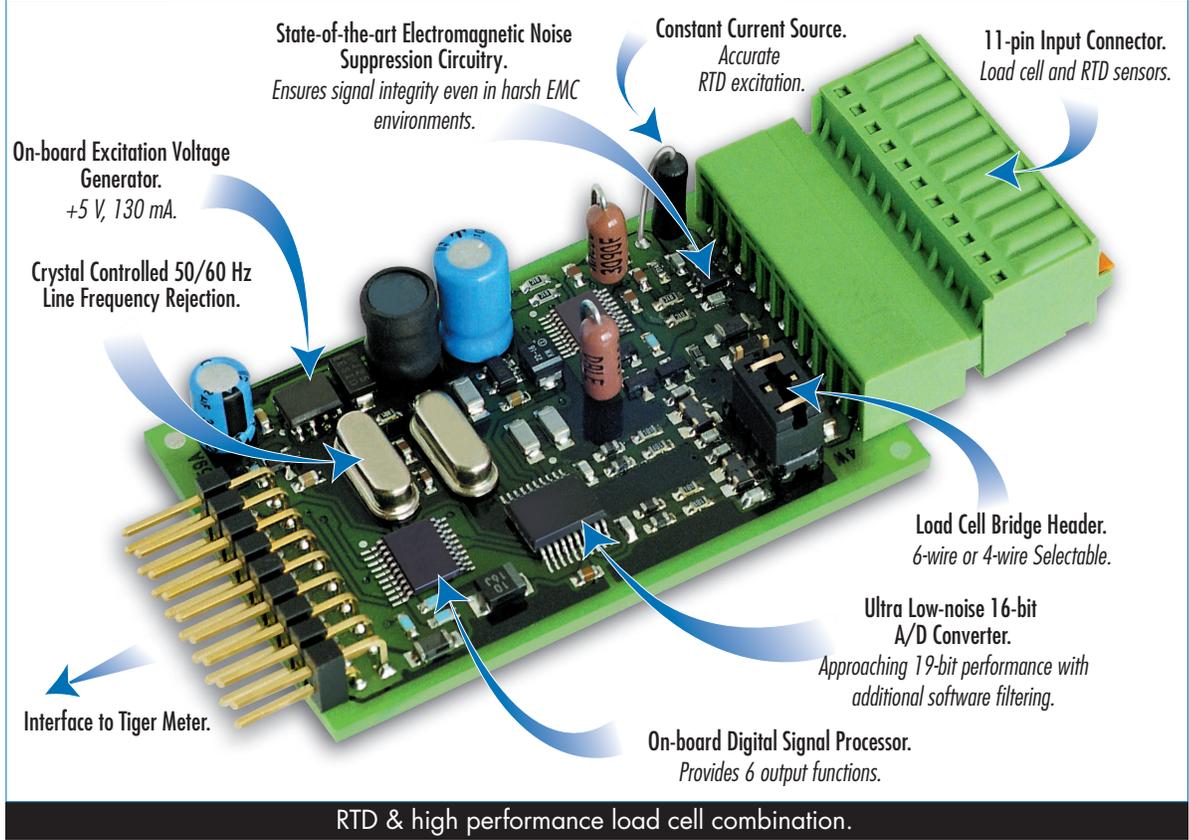


RTD & SMART 16-BIT LOAD CELL INPUT MODULE



A smart input module designed to monitor temperature using an RTD sensor and weight using a load cell. Ideal for applications that calculate fluid volume from weight and density measurements corrected for temperature changes.

Combined with the powerful Tiger 320 Series programmable meter controller, continuous monitoring and control of accurate volume versus cost calculations are a reality.

Input Module
Order Code Suffix
ISSB (50/60 Hz)



Hardware Module Specifications

RTD (CH1)	
Excitation	1.5 mA DC continuous.
Sensor Types	Pt (100 Ω) 385 & 395, Ni 120 & Cu 10.
Wiring	3-wire excitation & lead compensation.
Load Cell (CH2 / CH3 / CH4)	
Excitation	5 V DC, 130 mA maximum.
Input Range	Software selectable for sensors 1 mV/V to 20 mV/V.
Input Sensitivity	0.08 μV/ count maximum.
Zero Drift	± 40 nV/°C typical.
Span Drift	± 5 ppm/°C of full scale maximum.
Non-linearity	± 0.003% of full scale maximum.
Input noise	160 nV pp typical at 1 Hz output rate.
Signal Processing Rate	50 Hz maximum, 1 Hz minimum.
Wiring	4-wire & 6-wire selectable.
Guard	Shield 2.5 V common mode voltage.

Software Module Features

Load Cell	
Dual Output Rates	Rapid and average response outputs.
Peak & Valley Outputs	Monitoring over and under-shoots.
Capture Output	Hardwire signal capture.
Rate of Change Output	Useful for fine tuning reaction times.
Line Frequency Rejection	50/60 Hz selectable.

LOAD-CELL PRESSURE

TEMPERATURE T/C, RTD

Connector Pinouts

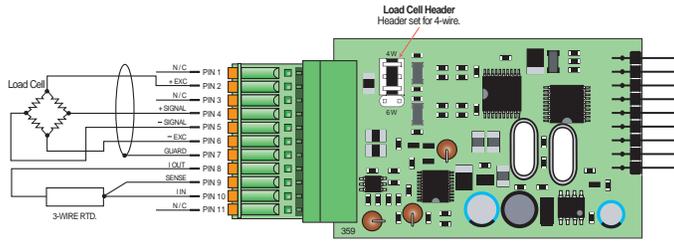


Figure 1 – ISSB Input Module Showing 4-wire Load Cell and 3-wire RTD Configuration

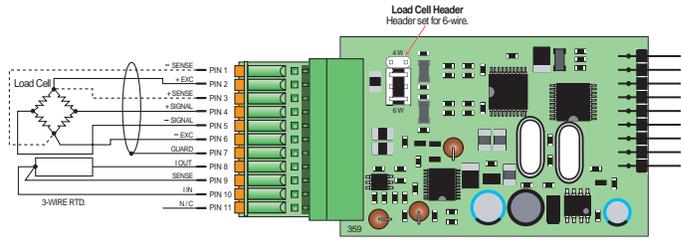


Figure 2 – ISSB Input Module Showing 6-wire Bridge and 3-wire RTD Configuration

Smart Setup Registers

The meter uses three smart setup registers to configure all smart input modules. The ISSB input module requires only **smart register 1** to be set up.

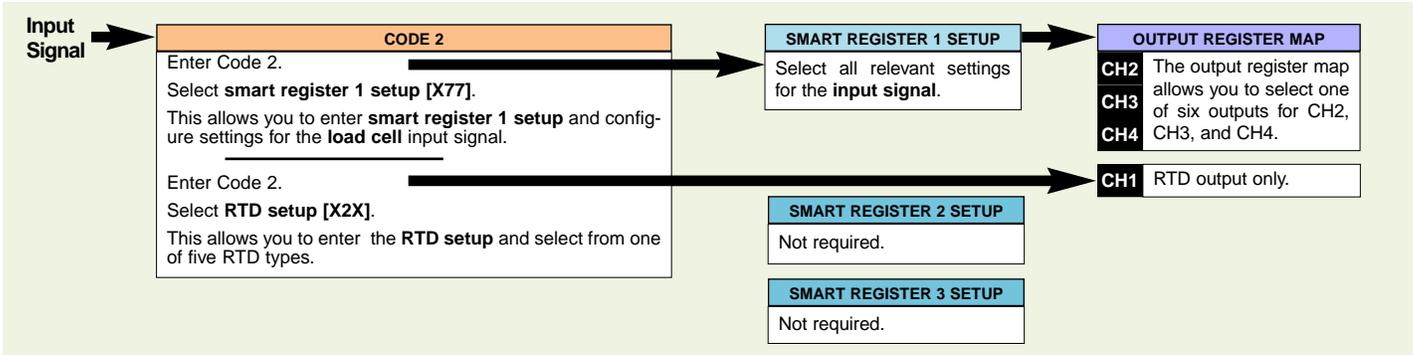
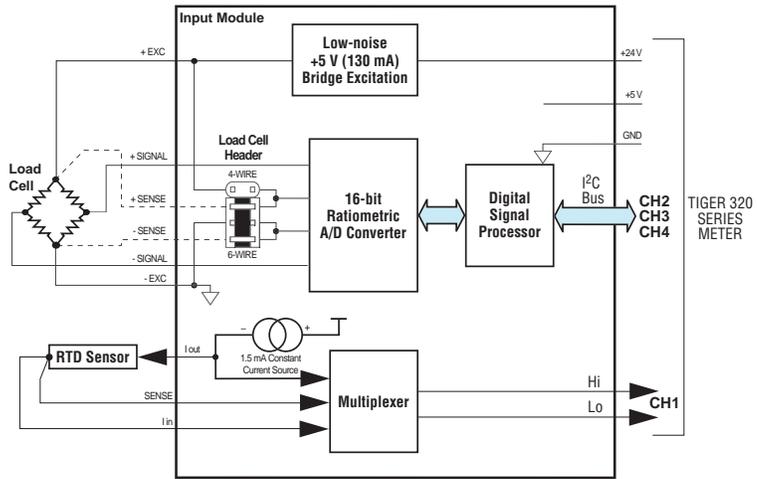


Figure 3 – ISSB Smart Setup Registers Operational Flow Diagram

Internally, the RTD input is automatically assigned to channel 1 (CH1) and must be set up through Code 2. The RTD input feeds directly through the input module multiplexer to the meter's 17-bit A/D converter, and then to the microprocessor for further processing.

The load cell input is processed in the input module's 16-bit A/D converter and digital signal processor. It is then fed to some or all of the three remaining channels, CH2, CH3, CH4, where one of six outputs can be selected for each channel from the output register map. Smart register 1 must be set up for the load cell to define the line frequency rejection, the sensor input in millivolts per volt, and the output rate.

Figure 4 – ISSB Smart Setup Registers – Signal Flow Diagram



Programming Quick Start Guide

Load Cell Setup

- 1 Press the **P** and **↑** buttons at the same time to enter the main programming mode.
- 2 Press the **P** button three times to enter Code 2. Set Code 2 to [X77].

Cod_2 [X7X]

This setting enters the **smart register 1** code setup menu of the **load cell** input.

FIRST DIGIT
TIGER PROCESSING RATE
0 10 Hz
1 10 Hz
2 100 Hz
3 100 Hz

SECOND DIGIT
MEASUREMENT TASK
0 Voltage, Current
1 TC (3rd digit selects type of TC)
2 RTD 3-wire (3rd digit selects type of RTD)
3 RTD 2- or 4-wire (3rd digit selects type of RTD)
4 Frequency
5 Period
6 Counter
7 Smart Input Module

THIRD DIGIT
OUTPUT REGISTER MAP
0 Averaged signal
1 Rapid response signal*
2 Peak signal*
3 Valley signal*
4 Capture signal**
5 Rate of change signal
6 -
7 Smart input module register 1 code setup

* Signal output at A/D sampling rate.
** Hardware initiated from meter capture pin.



Note the output register map is different for each smart input module.

- 3 Press the **P** button.

577E 1 000

This menu provides settings unique to **smart register 1** of input module ISSB.

FIRST DIGIT
LINE FREQUENCY
0 60 Hz rejection
1 -
2 50 Hz rejection
3 -

SECOND DIGIT
LOAD CELL INPUT mV/V (5 V Exc.)
0 1 mV/V
1 2 mV/V
2 3 mV/V
3 20 mV/V
4 -
5 -
6 -
7 -

THIRD DIGIT
OUTPUT RATE
0 1 Hz averaged: 50/60 Hz rapid response
1 10 Hz: 50/60 Hz rapid response
2 -
3 50/60 Hz averaged: 800/900 Hz rapid response
4 -
5 -
6 -
7 -

- 4 Using the **↑**/**↓** buttons, select the relevant line frequency rejection, load cell input, and output rate settings.

- 5 Press the **P** button. The display returns to [Cod_2] [X77]. **Cod_2** X77

RTD Setup

- 6 Using the **↑**/**↓** buttons, set Code 2 to [X2X] to select a 3-wire RTD sensor for the CH1 measurement task. In the 3rd digit, select the RTD type.

Cod_2 X2X

FIRST DIGIT
TIGER PROCESSING RATE
0 10 Hz
1 10 Hz
2 100 Hz
3 100 Hz

SECOND DIGIT
MEASUREMENT TASK
0 Voltage, Current
1 TC (3rd digit selects type of TC)
2 RTD 3-wire (3rd digit selects type of RTD)
3 RTD 2- or 4-wire (3rd digit selects type of RTD)
4 Frequency
5 Period
6 Counter
7 -

THIRD DIGIT
OUTPUT REGISTER MAP
0 Resistance
1 RTD Pt 100 Ω (385)
2 RTD Pt 100 Ω (392)
3 RTD Zn 100 Ω (120)
4 RTD Cu 10 10 Ω
5 -
6 -
7 -

- 7 Press the **P** button to save the settings.

Press the **P** and **↑** buttons at the same time to save the RTD Code 2 settings and return to the operational display.

Select a Load Cell Channel

Select the load cell output register for CH2, CH3, or CH4

- 8 Press the **P** and **↑** button at the same time again to re-enter the main programming mode.

- 9 Press the **P** button five times to enter Code 4.

- 10 To select an output register for CH2, enter Code 4 and select the required register map settings for **CH2** in the 2nd digit.

Note, the 1st and 3rd digits must be set to 0.

CH2 Cod_4 0X0

FIRST DIGIT
MEASUREMENT TASK
0 Voltage, Current
1 TC (type as per 2nd digit)
2 RTD (type as per 2nd digit)
3 Second Digital Input Channel (type as per 2nd digit)

SECOND DIGIT	FOR VOLTAGE & CURRENT	
0 Sensor 2 Input Disabled	*Note: The logic for CH2 is not the same as CH3, or CH4. The 1st and 3rd digits must both be set to 0. Selecting 040 to 070 in the 2nd digit of Code 4 directly selects one of the following settings in the output register map (3rd digit):	
1 Direct (no post processing)	2nd Digit	Output Register Map
2 Square Root of Sensor 2 Input	4 selects	0 Averaged signal
3 Inverse of Sensor 3 Input	5 selects	1 Rapid response signal
4 Output Register 1 (smart module)*	6 selects	2 Peak signal
5 Output Register 2 (smart module)*	7 selects	3 Valley signal
6 Output Register 3 (smart module)*		
7 Output Register 4 (smart module)*		

Note the capture and rate of change registers can not be selected in Code 4 for CH2.

- 11 If required enter Code 5 and select the required post processing setting for **CH3** in the 2nd digit and the required output register map setting in the 3rd digit.

CH3 Cod_5 X7X

FIRST DIGIT
CH3 INPUT POST PROCESSING
0 Direct Display of Input (no processing)
1 Square Root of Sensor 3 Input
2 Inverse of Sensor 3 Input
3 Meters with 4 kB memory NO Linearization Meters with 32 kB memory 32-point Linearization of Sensor 3 Input using Table 3
Note: All linearization tables are set up in the Calibration Mode [24X].

THIRD DIGIT
OUTPUT REGISTER MAP
0 Averaged signal
1 Rapid response signal*
2 Peak signal*
3 Valley signal*
4 Capture signal**
5 Rate of change signal
6 -
7 Smart input module register 1 code setup

Note the register map is different for each smart input module type.

* Signal output at A/D sampling rate.
** Hardware initiated from meter capture pin.

From Procedure 12, Page 4

- 12 If required enter Code 6 and select the required post processing setting for CH4 in the 1st digit and the required register map setting in the 3rd digit.

CH4 Cod_6 X7X

FIRST DIGIT
SENSOR 4 INPUT POST PROCESSING
0 Direct Display of Input (no processing)
1 Square Root of Sensor 4 Input
2 Inverse of Sensor 4 Input
3 Meters with 4 kB memory
NO Linearization
Meters with 32 kB memory
32-point Linearization of Sensor 4 Input using Table 4
Note: All linearization tables are set up in the Calibration Mode [24X].

To Procedure 11, Page 3

- 13 Press the **P** button to save the settings.

- 14 Press the **P** and **↑** buttons at the same time to return to the operational display.

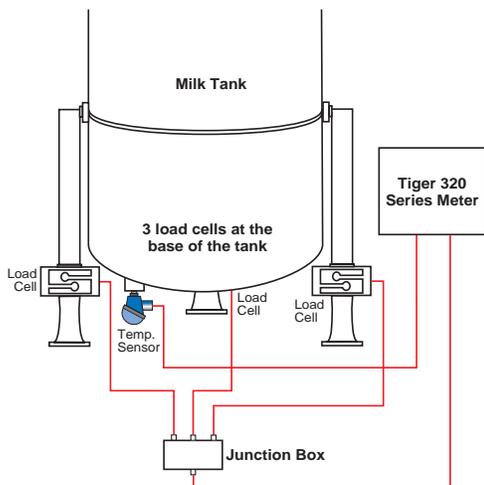


Figure 5 – Example Milk Dispensing Tank

Example Setup Procedure

The volume of milk in a dispensing tank must be known as payment to the dairy farmer is on a per volume basis (See Figure 5).

Each foot of the tank is mounted on a 20 mV/V load cell. Each load cell is connected in parallel at a junction box to supply an averaged weight signal to the Tiger 320 Series controller.

An RTD 385 Pt 100 Ω sensor monitors the liquid temperature. As volume changes slowly with temperature, an output rate of 1 Hz averaged is sufficient for the load cell signal.

- 1 Select line frequency rejection as 50 Hz input for a 20 mV/V load cell averaged signal input with a 1 Hz output rate in smart register 1:

In **CODE 2** select **X77** then press **P** button.

Display toggles between **SMt1** **000**

Set **SMt1** to **230**

- 2 Select 3-wire RTD 385 probe for CH1:

In **CODE 2** select **X21**

- 3 Select the load cell average output weight for CH2:

In **CODE 4** select **040**

Customer Configuration Settings:

RTD only

CH1 Cod_2 2

Load Cell only

Cod_2 7 7

SP7E1

CH2 Cod_4 0 0

CH3 Cod_5 7

CH4 Cod_6 7

WARRANTY

Texmate warrants that its products are free from defects in material and workmanship under normal use and service for a period of one year from date of shipment. Texmate's obligations under this warranty are limited to replacement or repair, at its option, at its factory, of any of the products which shall, within the applicable period after shipment, be returned to Texmate's facility, transportation charges pre-paid, and which are, after examination, disclosed to the satisfaction of Texmate to be thus defective. The warranty shall not apply to any equipment which shall have been repaired or altered, except by Texmate, or which shall have been subjected to misuse, negligence, or accident. In no case shall Texmate's liability exceed the original purchase price. The aforementioned provisions do not extend the original warranty period of any product which has been either repaired or replaced by Texmate.

USER'S RESPONSIBILITY

We are pleased to offer suggestions on the use of our various products either by way of printed matter or through direct contact with our sales/application engineering staff. However, since we have no control over the use of our products once they are shipped, NO WARRANTY WHETHER OF MERCHANTABILITY, FITNESS FOR PURPOSE, OR OTHERWISE is made beyond the repair, replacement, or refund of purchase price at the sole discretion of Texmate. Users shall determine the suitability of the product for the intended application before using, and the users assume all risk and liability whatsoever in connection therewith, regardless of any of our suggestions or statements as to application or construction. In no event shall Texmate's liability, in law or otherwise, be in excess of the purchase price of the product.

Texmate cannot assume responsibility for any circuitry described. No circuit patent or software licenses are implied. Texmate reserves the right to change circuitry, operating software, specifications, and prices without notice at any time.

TEXMATE INC

995 Park Center Drive • Vista, CA 92081-8397

Tel: 1-760-598-9899 • USA 1-800-839-6283 • That's 1-800-TEXMATE

Fax: 1-760-598-9828 • Email: sales@texmate.com • Web: www.texmate.com

Texmate has facilities in Japan, New Zealand, Taiwan, and Thailand. We also have authorized distributors throughout the USA and in 28 other countries.

For product details visit www.texmate.com

Local Distributor Address