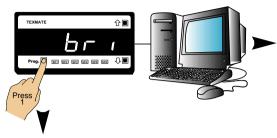
Tiger 320 Series PROGRAMMING CODE SHEET

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Front panel programming

This programming code sheet (PCS) is a quick reference document that allows you to quickly view the meter's programming codes.

When you become familiar with the meter and the programming code structure, the PCS can be used in place of the user manual.



Note:

All displays shown in this code sheet are for a 5-digit, 7-segment display. 6 or 8-digit and alphanumeric displays will be slightly different.

To configure the meter's programming codes, the meter uses the three right-hand side display digits. These are known as the 1st, 2nd, and 3rd digits and can be seen in the diagram opposite.

Operational Display

1st 2nd 3rd
Digit Digit Digit

The logic diagram on Page 4 shows the code structure of the Tiger 320 Series meter range. Also, the difference between the E and T version of the Tiger range is described. The diagrams on the following pages show the three-digit settings available for each code.

Programming via PC

Meter configuration utility program

With a serial output module installed, the meter can be fully configured through the meter configuration utility program. In addition to all application function settings, the configuration program also provides access to added features such as:

- · Code blanking.
- Display text editing.
- Configuration data copying.
- Downloading macros to the meter.

Code blanking

Code blanking blanks out all function codes not required by the application. This means that specific procedures such as recalibration and setpoint reprogramming can be achieved in a few simple steps from the front panel buttons.

 To turn code blanking and macro settings OFF, carry out the Code Blanking and Macro Check on Page 3.

Display text editing

This function allows displayed text, such as setpoint titles, to be edited to suit your applications.

For example, a setpoint could be edited to read [TNK_Lo] for tank level low, or [brKoF] for brake off.

Configuration data copying

This function allows the current meter configuration settings to be copied and saved for later referral or for restoration.

Macros

Texmate has a growing library of macros to suit a wide range of standard customer applications. Macros can be installed in the meter, via the compiler or configuration program, and run automatically when the meter is powered up.

Tamper-proof settings

All Tiger 320 Series meters have tamper-proof lockout switches to prevent users' configuration settings from being inadvertently changed.

Code blanking is also used (via the PC) to blank out codes not used, making them operator tamper-proof, but leaving selected codes open for operator adjustment.



Programming Tips

- 1) Use the P button to step through the codes of the **Main** or **Setpoint** Programming Mode.
- To save a Main Programming Mode code setting and return directly to the operational display, press the P button and then the P and buttons at the same time.
- 3) To save a Setpoint Programming Mode setting and return directly to the operational display, press the P button and then the P and I buttons at the same time.
- 4) When configuring the three-digit code and setpoint settings, pressing the

 and

 buttons at the same time increases the displayed parameter in increments of 100 counts.



Initial Setup Procedures

Before configuring the meter, carry out the following meter configuration checks:

- · Model and software code version check.
- · Code blanking and macro check.

After powering-up the meter, check the model and software code version number and note this below.

| Model No: |
|----------------------|
| Software Version No: |
| Customer ID: |
| Macro ID: |
| |

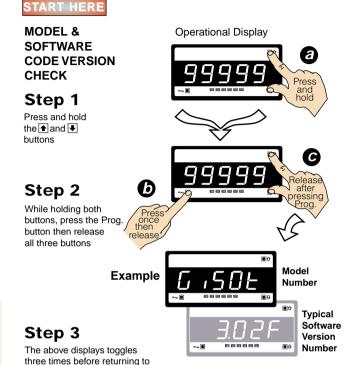
Model and Software Code Version Check

The meter model and software code version number can be checked at any time while in the operational display using the following procedure.



Programming Tip

The Model and Software Code Version checking procedure can be performed at any time without interfering with other configuration settings.



the operational display





Operational Display

Code Blanking and Macro Check

Tiger 320 Series meters have the ability to hide (blank out) all or some programming codes, making them tamper-proof. This can only be done using the Meter Configuration Utility program.

With code blanking turned ON, all main and setpoint codes that have been blanked out during factory programming are hidden, preventing them from being reprogrammed. Any codes that have not been blanked out are still visible and can be reprogrammed.

Turning code blanking OFF means all meter programming codes are visible when you enter the programming modes and can be reprogrammed.

A macro is a set of commands that run automatically when the meter is powered up. Texmate has a growing library of macros to suit a wide range of standard customer applications.

Macros can be installed in the meter at the factory during initial programming or by the customer at some later date. Macros are written and compiled using the Tiger Development System (TDS) compiler program, and loaded into the meter using either the ompiler program or the configuration program.

Turning the macro OFF means that the meter will not perform the automatic commands pre-programmed to run with the macro.

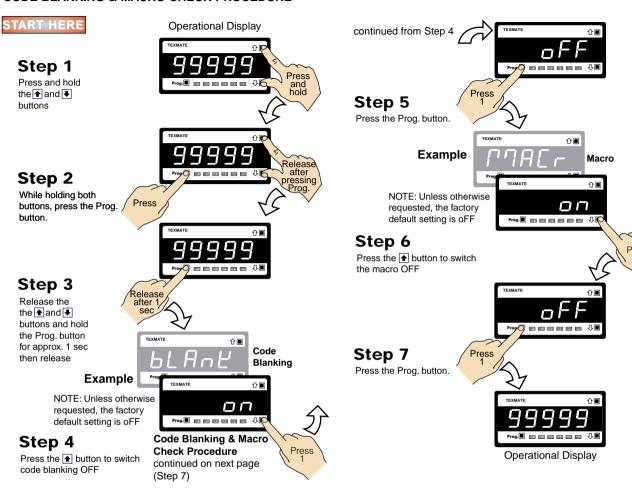
Unless requested to blank out all or some programming codes and/or run a macro, Texmate program the meter in the code blanking OFF and macro OFF (default) setting.

To turn the code blanking and macro settings from ON to OFF carry out the following procedure:

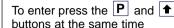
Programming Tip

Code Blanking and Macro ON/OFF settings revert to the meter's original configuration settings when the meter is powered off and on.

CODE BLANKING & MACRO CHECK PROCEDURE



Tiger 320 Series Code Logic Diagram





To enter press the P and ▶ buttons at the same time

Main Programming Mode

[bri]

Display Brightness

Allows you to adjust the display brightness in a range of 8 settings. 0 being dull, 7 being bright.



Calibration Modes for Input and Output

See Page 2 for code settings to calibrate the meter's input and output signals.



Code 1 - Display Configuration

See Page 3 for code settings to configure the setpoint annunciators and other display functions.

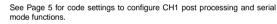


Code 2 - CH1 Measurement Task & Sampling Rate

See Page 4 for code settings to configure the CH1 measurement task and sampling rate.



Code 3 - CH1 Post Processing & Serial Mode Functions



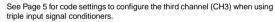


Code 4 - CH2 Measurement Task & 32-point Linearization

See Page 5 for code settings to configure the second channel (CH2) measurement task and 32-point linearization settings when using dual input signal conditioners.

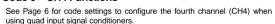


Code 5 - CH3 Functions





Code 6 - CH4 Functions



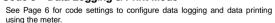


Code 7 - Result Processing

See Page 6 for code settings to configure the meter for processing the result of CH1 and CH2.



Code 8 - Data Logging & Print Mode





Code 9 - Functions for Digital Input Pins

See Page 6 for code settings to configure the meter for inputs from external sources through the digital input pins.



[Cod_9]

Code 10 - Bargraph Setup

See Page 7 for code settings to configure the meter's bargraph display.

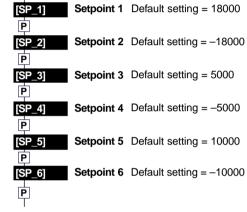


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Setpoint Programming Mode

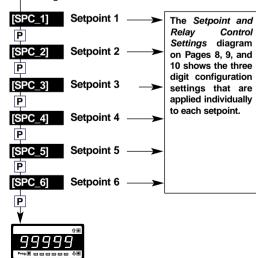
Setpoint Activation Values Mode

Enter these menus to set setpoint (SP) activation values



Setpoint & Relay Control Settings Mode

Enter these menus to configure SP control settings



E/T Versions of Tiger 320 Series Programmable Meter Controller

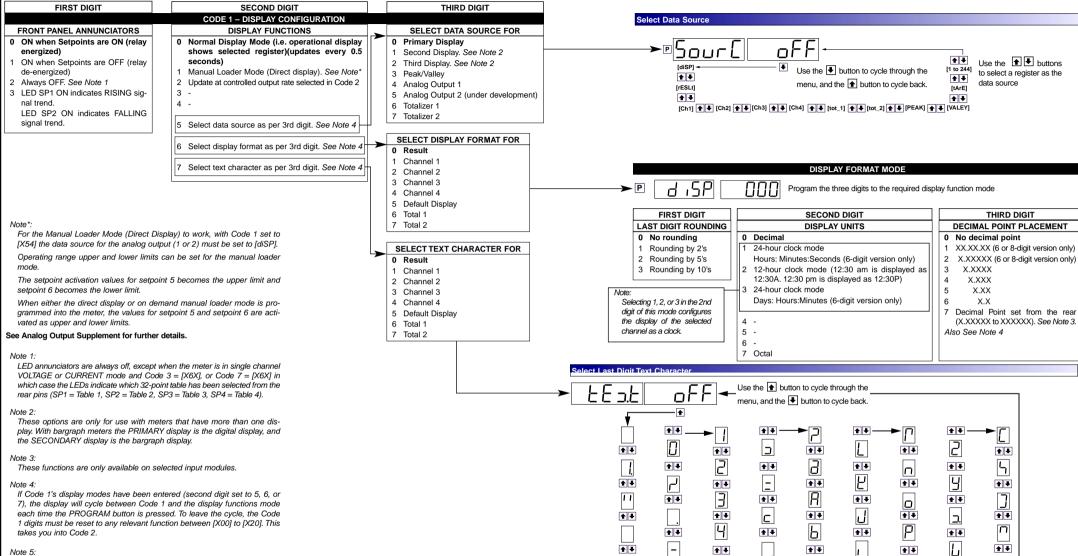
Tiger 320 Series Programmable Meter Controllers (PMCs) come in two versions: the economy E version, or the top-of-the-line T version.

The standard E version comes with 4 kilobits of EEPROM installed, whereas the standard T version comes with 32 kilobits of EEPROM Installed. Also, the T version can have a macro installed.

The standard 4-kilobit E version can be upgraded to 32 or 512 kilobits. The standard 32-kilobit T version can be upgraded to 512 kilobits. The amount of EEPROM installed in the controller determines the range of functions it is capable of performing. The following table lists the functions that require specific amounts of memory.

| Version | Memory (kilobits) | Functions | Remarks | | | | |
|---------|----------------------|------------------------|---|--|--|--|--|
| E | 4 (standard) | 1 linearization table | be applied to chan- nels 1 to 4 and result. | | | | |
| | 32 | 4 linearization tables | Tables 1 to 4 are available to be applied to channels 1 and 2 and result. | | | | |
| | | | Table 3 can be applied to channel 3. | | | | |
| | | | Table 4 can be applied to channel 4. | | | | |
| | | | All four tables can be cascaded to form a single 125-point linearization table available to be applied to channels 1 and 2 and result. | | | | |
| | 512 | Data logging | With 512 kilobits installed, the controller can perform data logging functions along with complete linearization functionality. With a real-time clock installed, date and time stamps can be included. | | | | |
| Т | 32 (standard) | 4 linearization tables | As for E version with 32 kilobits installed. | | | | |
| | | Macro programming | A macro can be pro- grammed to suit a user's logic control application. | | | | |
| | 512 | Data logging | As for E version with 512 kilobits installed, but with macro programming functionality available. | | | | |

CODE 1



If only 4 kB memory installed, functions 2 to 6 are not available in:

- Code 3 second digit.
- Code 4 third digit.
- · Code 7 second digit.

Note 6:

These functions are not available on all models and in some cases require additional hardware

Note 7:

For future development.

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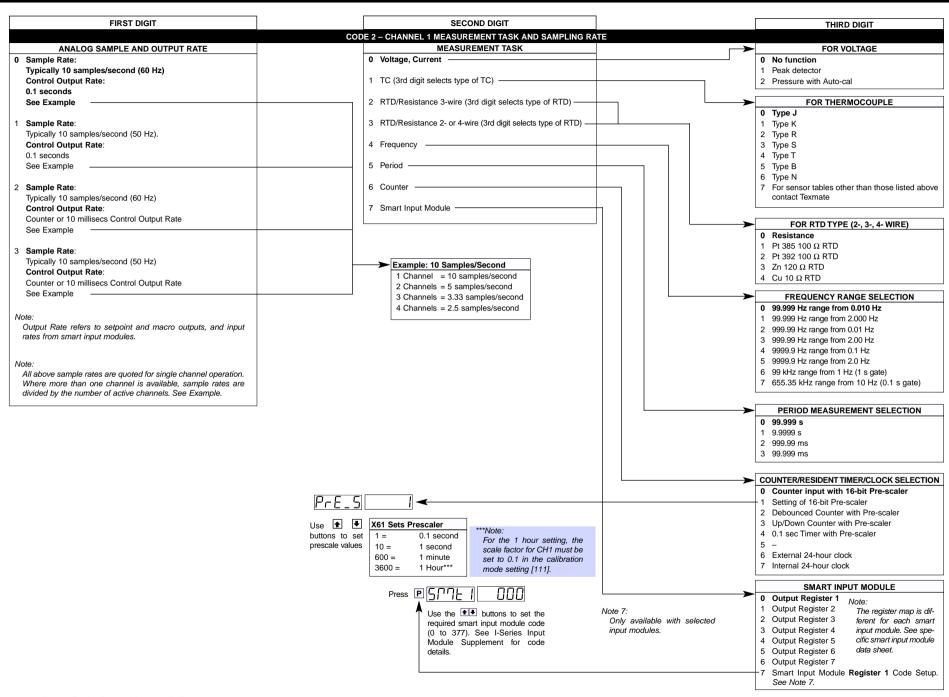
1

4

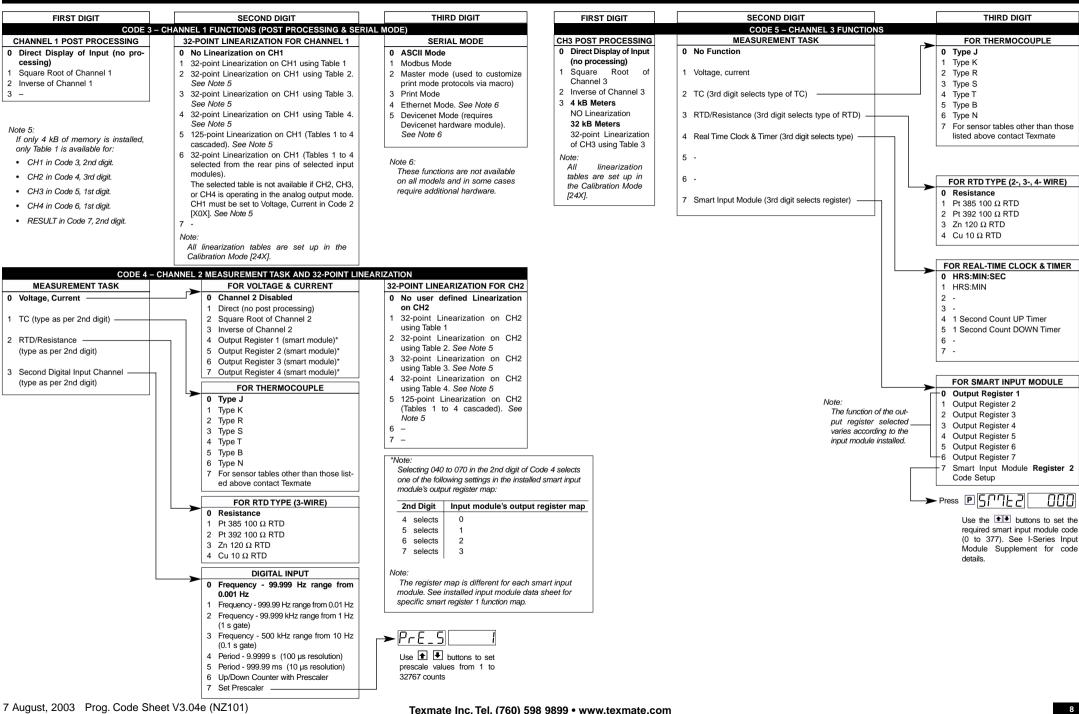
4

4

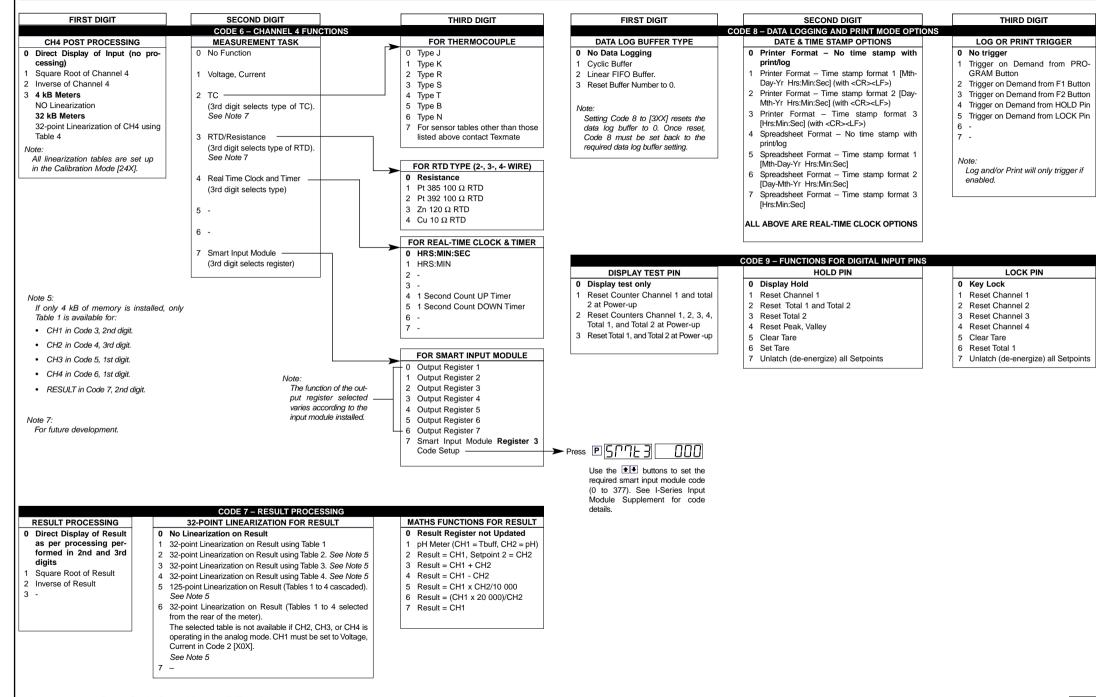
CODE 2



CODES 3 to 5



CODES 6 to 9



SETPOINT PROGRAMMING MODE - SPC 1 to SPC 6

Setpoint Setup Sequence

► Follow These Steps <

The following procedures are written for SP1, all other setpoints are configured in a similar manner.

 Press the P and D buttons at the same time. This enters the setpoint programming mode. The display toggles between [SP_1] and [18000].

This is SP1 of the **Setpoint Activation Values Mode**. Use the **♠** and **●** buttons to set SP1 or the **P** button to move to the required setpoint.

 After all required setpoint activation values have been set, press the button until [SPC_1] appears. This is the Setpoint & Relay Control Settings Mode.

SPC_1 is the **setpoint and relay control settings** programming menu for SP1. Set the three digits according to the codes in the *Setpoint and Relay Control Function Settings* opposite in the following order:

Third Digit - Setpoint Delay Mode

Set to [XX5] and program the hysteresis, deviation, or PID functions as required for SP1.

Reset back to [XX0].

Third Digit - Setpoint Timer Mode

Set to [XX6] and program the timer mode functions as required for SP1.

Reset back to [XX0].

Third Digit - Setpoint Reset & Trigger Functions

Set to [XX7] and program the reset and trigger functions as required for SP1.

Reset back to [XX0].

Second Digit - Setpoint Activation Source Mode

Set to [X1X] to select the setpoint activation source for SP1 from any channel or selected register shown above. Reset back to [X0X].

If the SP source is from an external digital input, set to one of either [X2X] to [X7X] to select the setpoint activation source from one of six digital inputs (2 to 7). See *Note at 2nd digit.

First Digit - Relay Energize Mode

Select the relay energize mode for SP1 from 0 to 3.

Third Digit - Relay Latching & Manual Reset Functions

Program the third digit setpoint relay latching and manual reset functions between 0 to 4 as required.

- 3) Press the P button to move to move to [SPC_2]
- 4) Repeat Step 2 for all required setpoints.

PRINT DIGIT Relay Energize Function O Energizes ABOVE setpoint value HYSTERESIS selected – relay energizes ABOVE setpoint value

HYSTERESIS selected – relay energizes AT OR ABOVE setpoint value plus hysteresis counts. De-energizes BELOW setpoint value minus hysteresis counts.

Note:

If hysteresis set with ZERO counts, relay energizes AT OR ABOVE the setpoint value.

DEVIATION selected – relay energizes INSIDE deviation band (setpoint ± deviation counts). De-energizes OUTSIDE deviation band (setpoint ± deviation counts).

PID selected - controls ABOVE setpoint value.

1 Energizes BELOW setpoint value

HYSTERESIS selected – relay energizes BELOW setpoint value minus hysteresis counts. De-energizes AT OR ABOVE setpoint value plus hysteresis counts.

Note:

If hysteresis set with ZERO counts, relay energizes BELOW the setpoint value.

DEVIATION selected – relay energized OUTSIDE deviation band (setpoint ± deviation counts). De-energized INSIDE deviation band (setpoint ± deviation counts).

PID selected - controls BELOW setpoint value.

2 Energizes AT OR ABOVE setpoint value with FALLING INPUT SIG-NAL INITIAL START-UP INHIBIT

HYSTERESIS selected – relay energizes AT OR ABOVE setpoint value plus hysteresis counts with FALLING INPUT SIGNAL INITIAL START-UP INHIBIT. De-energizes BELOW setpoint value minus hysteresis counts with FALLING INPUT SIGNAL INITIAL START-UP INHIBIT.

Note:

If hysteresis set with ZERO counts, relay energizes AT OR ABOVE the setpoint value.

DEVIATION selected – relay energizes INSIDE deviation band (setpoint ± deviation counts) with FALLING INPUT SIGNAL INITIAL START-UP INHIBIT. De-energizes OUTSIDE deviation band (setpoint ± deviation counts) with FALLING INPUT SIGNAL INITIAL START-UP INLIBIT.

PID selected - controls ABOVE setpoint value.

3 Energizes BELOW setpoint value with RISING INPUT SIGNAL INI-TIAL START-UP INHIBIT

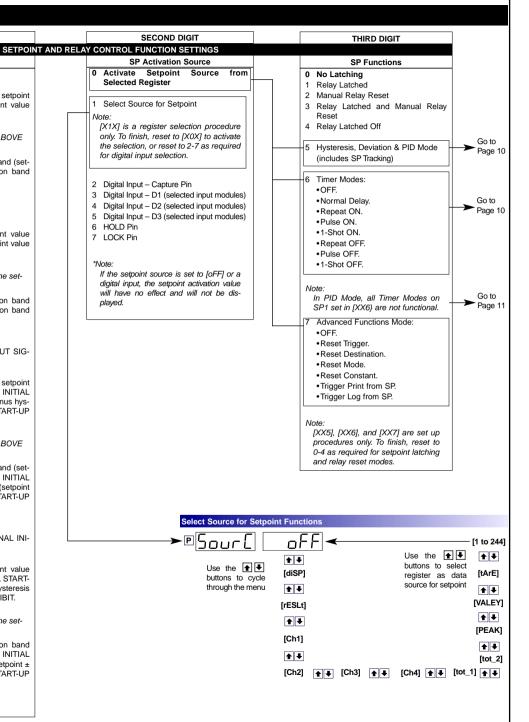
HYSTERESIS selected – relay energizes BELOW setpoint value plus hysteresis counts with RISING INPUT SIGNAL INITIAL START-UP INHIBIT. De-energizes BELOW setpoint value minus hysteresis counts with RISING INPUT SIGNAL INITIAL START-UP INHIBIT.

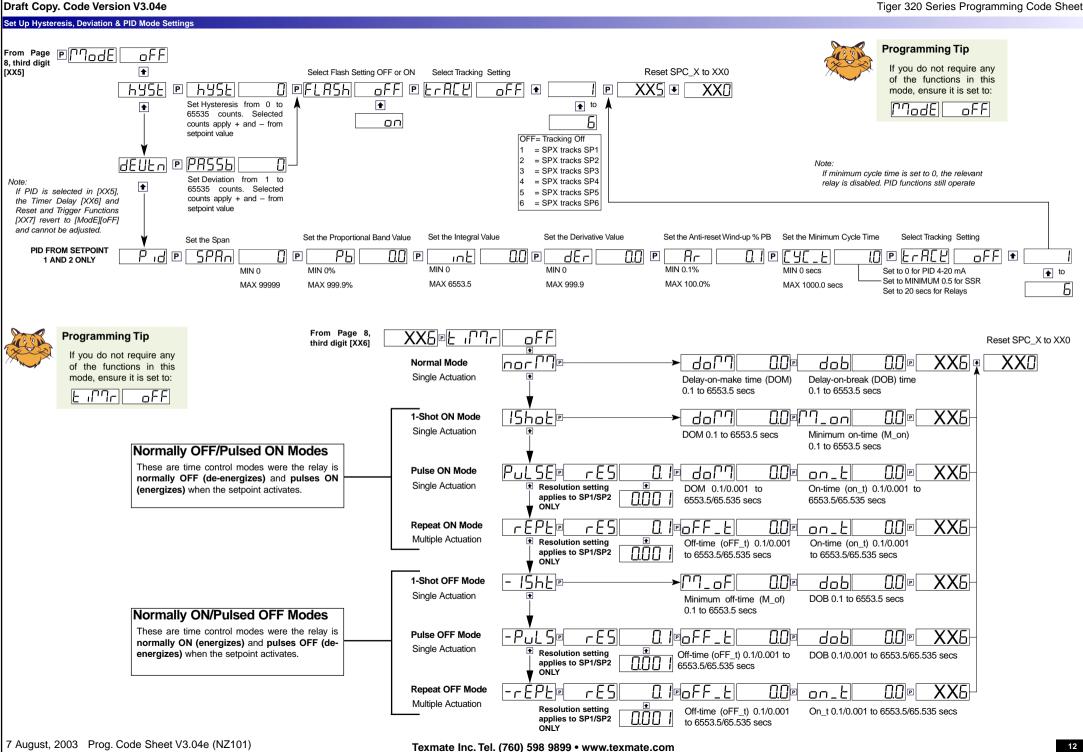
Note:

If hysteresis set with ZERO counts, relay energizes BELOW the setpoint value.

DEVIATION selected – relay energizes OUTSIDE deviation band (setpoint ± deviation counts) with RISING INPUT SIGNAL INITIAL START-UP INHIBIT. De-energizes INSIDE deviation band (setpoint ± deviation counts) with RISING INPUT SIGNAL INITIAL START-UP INHIBIT

PID selected - controls BELOW setpoint value.





Advanced Functions Mode – Set Up Register Reset and Setpoint Trigger Functions



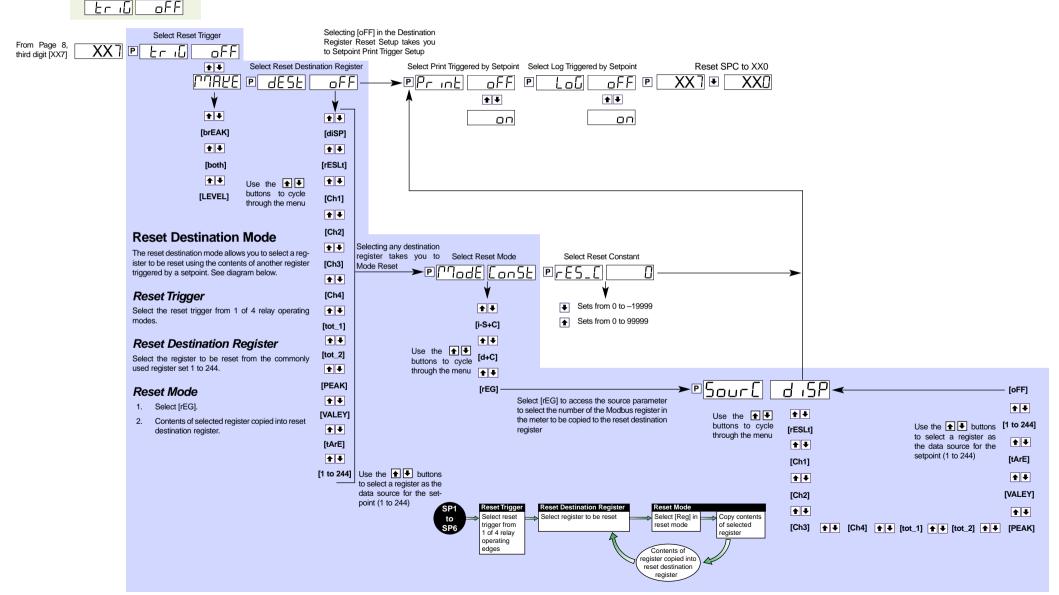
Programming Tip

If you do not require any of the functions in this mode, ensure it is set to:



Programming Tip

This mode can not be accessed if SPC_1 or SPC_2 is in the PID mode.



Customer Code Settings – Main Programming Mode

| CALIBRAT | ION MODE [| CAL] | | | | | |
|-----------|--------------|-----------|--|-------------|--------------|-----------|--|
| 1st DIGIT | 2nd DIGIT | 3rd DIGIT | SUB-SETTINGS | 1st DIGIT | 2nd DIGIT | 3rd DIGIT | SUB-SETTINGS |
| ON DEMAN | ND FUNCTIONS | | | CALIBRATI | ON PROCEDUR | RES | |
| | | RESULT | 010 020 SPAN INPUT 030 ZERO INPUT SPAN INPUT 040 CHANNEL 050 CHANNEL | Manual Cal | ibration | | 100 OFFSET SCALE 101 OFFSET SCALE 102 OFFSET SCALE 103 OFFSET SCALE 104 OFFSET SCALE |
| | | СH1 | 011 021 SPAN INPUT 031 ZERO INPUT SPAN INPUT 041 CHANNEL 051 CHANNEL | Two-point C | Calibration | | 110 ZERO INPUT SPAN INPUT 111 ZERO INPUT SPAN INPUT 112 ZERO INPUT SPAN INPUT 113 ZERO INPUT SPAN INPUT 114 ZERO INPUT SPAN INPUT |
| | | CH2 | 012 022 SPAN INPUT 032 ZERO INPUT SPAN INPUT 042 CHANNEL 052 CHANNEL | | nalog Output | | 121 ZERO INPUT 32°F SPAN INPUT 2500°F 122 ZERO INPUT 32°F SPAN INPUT 2500°F 123 ZERO INPUT 32°F SPAN INPUT 2500°F 151 CAL LOW OUTPUT CAL HIGH OUTPUT |
| | | CH3 | 013 023 SPAN INPUT 033 ZERO INPUT SPAN INPUT 043 CHANNEL CHANNEL CHANNEL | | | | 152 CAL LOW OUTPUT CAL HIGH OUTPUT |
| | | CH4 | 014 024 SPAN INPUT 034 ZERO INPUT SPAN INPUT 044 CHANNEL 054 CHANNEL | | | | |

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|------------|-------------------|---------------|--------------------------------------|
| | | | |
| CALIBRAT | TION MODE | [CAL] Con | tinued |
| 1st DIGIT | 2nd DIGIT | 3rd DIGIT | SUB-SETTINGS |
| RELATED | CALIBRATION | FUNCTIONS | |
| Serial Out | put | | 200 BAUD PARITY ADDRESS TIME DELAY |
| | | | 201 BAUD PARITY ADDRESS TIME DELAY |
| | | | 202 BAUD PARITY ADDRESS TIME DELAY |
| | | | 203 BAUD PARITY ADDRESS TIME DELAY |
| | | | 204 BAUD PARITY ADDRESS TIME DELAY |
| Auto Zero | Maintenance | | |
| | | | 210 AZ CAPTURE AZ MOTION AZ APERTURE |
| | | | 211 AZ CAPTURE AZ MOTION AZ APERTURE |
| | | | 212 AZ CAPTURE AZ MOTION AZ APERTURE |
| | | | 213 AZ CAPTURE AZ MOTION AZ APERTURE |
| | | | 214 AZ CAPTURE AZ MOTION AZ APERTURE |
| Averaging | Samples & Ave | eraging Windo | w |
| | | | 220 AVERAGE SAMPLES AVERAGE WINDOW |
| | | | 221 AVERAGE SAMPLES AVERAGE WINDOW |
| | | | 222 AVERAGE SAMPLES AVERAGE WINDOW |
| | | | 223 AVERAGE SAMPLES AVERAGE WINDOW |
| | | | 224 AVERAGE SAMPLES AVERAGE WINDOW |
| K Factor 8 | & Totalizer Cutof | f | |
| | | | 231 SCALE FACTOR CUTOFF |
| | | | 232 SCALE FACTOR CUTOFF |
| 32-point L | inearization Tab | oles | |
| | | | 240 MODE |
| | | | 241 MODE |
| | | | 242 MODE |
| | | | 243 MODE |
| | | | 244 MODE |
| Scale Ana | log Output | | OTAL TERROL |
| | | | 251 ZERO FULL SCALE |
| | | | 252 ZERO FULL SCALE |

Tiger 320 Series Programming Code Sheet

| Draft Copy | . Code Versi | ion V3.04e | | | | | | | | | Tiger 320 Ser | ries Programming Cod | le Sheet |
|------------|--------------|------------|---------------|--------------|--------------------|--------------------------------|-----------|-----------|-----------|--------------------|----------------|----------------------|----------|
| CODE 4 | | | | CODE 2 | | | CODE 40 | | | | | | |
| CODE 1 | [| | | CODE 2 | | | CODE 10 | [| | | | | |
| 1st DIGIT | 2nd DIGIT | 3rd DIGIT | SUB-SETTINGS | 1st DIGIT 2n | d DIGIT 3rd DIGIT | PRESCALER | 1st DIGIT | 2nd DIGIT | 3rd DIGIT | | | | |
| | | | | | | | | | | SCALING FOR LINEAR | R BARGRAPH | | |
| | | | X50 SOURCE | CODE 3 | | | BARGRAP | PH COLORS | | 3X0 BAR LOW | BAR HIGH | BAR NOMINAL | |
| | | | X51 SOURCE | 1st DIGIT 2n | ad DIGIT 3rd DIGIT | | 2XX COL | OR 1 | | 3X1 BAR LOW | BAR HIGH | BAR NOMINAL | |
| | | | X52 SOURCE | | | | COL | OR 2 | | SCALING FOR LOGIRI | THMIC BARGRAPH | | |
| | | | X53 SOURCE | CODE 4 | | | COL | OR 3 | | 3X3 REFERENCE | BAR NOMINA | AL | |
| | | | X54 SOURCE | 1st DIGIT 2n | d DIGIT 3rd DIGIT | PRESCALER | COL | OR 4 | | 3X4 REFERENCE | BAR NOMINA | AL | |
| | | | X55 SOURCE | | | | COL | OR 5 | | 3X5 REFERENCE | BAR NOMINA | AL . | |
| | | | X56 SOURCE | CODE 5 | | | COL | OR 6 | | 3X6 REFERENCE | BAR NOMINA | AL . | |
| | | | X57 SOURCE | 1st DIGIT 2n | d DIGIT 3rd DIGIT | SMART INPUT MODULE SETTINGS | COL | OR 7 | | 3X7 REFERENCE | BAR NOMINA | AL . | |
| | | | X60 DISPLAY | | | SETTINGS | | | | | | | |
| | | | X61 DISPLAY | | | | | | | | | | |
| | | | X62 DISPLAY | CODE 6 | | | | | | | | | |
| | | | X63 DISPLAY | 1st DIGIT 2n | d DIGIT 3rd DIGIT | SMART INPUT MODULE | | | | | | | |
| | | | X64 DISPLAY | | | SETTINGS | | | | | | | |
| | | | X65 DISPLAY | | | | | | | | | | |
| | | | X66 DISPLAY | CODE 7 | | | | | | | | | |
| | | | X67 DISPLAY | 1st DIGIT 2n | ad DIGIT 3rd DIGIT | | | | | | | | |
| | | | X70 CHARACTER | | | | | | | | | | |
| | | | X71 CHARACTER | CODE 8 | | | | | | | | | |
| | | | X72 CHARACTER | | nd DIGIT 3rd DIGIT | | | | | | | | |
| | | | X73 CHARACTER | | | | | | | | | | |
| | | | X74 CHARACTER | CODE 9 | | | | | | | | | |
| | | | X75 CHARACTER | | nd DIGIT 3rd DIGIT | | | | | | | | |
| | | | X76 CHARACTER | | | | | | | | | | |

X77 CHARACTER

Customer Code Settings – Setpoint Programming Mode

SP ACTIVATION VALUES SETPOINT VALUE SP1 SP2 SP3 SP4

SP5 SP6

SETPOINT & RELAY CONTROL SETTINGS MODE SPC_1 TO SPC_6

| SELECT DATA SOURCE | DELAY MODE SETTINGS | | |
|--------------------|---------------------|----------------------|-------------|
| SPC_1 _ 1 | SPC_15 HYSTERESIS | ANNUNCIATOR FLASHING | SP TRACKING |
| SPC_2 _ 1 | SPC_25 HYSTERESIS | ANNUNCIATOR FLASHING | SP TRACKING |
| SPC_3 _ 1 | SPC_35 HYSTERESIS | ANNUNCIATOR FLASHING | SP TRACKING |
| SPC_4 _ 1 _ | SPC_45 HYSTERESIS | ANNUNCIATOR FLASHING | SP TRACKING |
| SPC_5 _ 1 _ | SPC_5 HYSTERESIS | ANNUNCIATOR FLASHING | SP TRACKING |
| SPC_6 _ 1 _ | SPC_65 HYSTERESIS | ANNUNCIATOR FLASHING | SP TRACKING |

| DEVIATION | ANNUNCIATOR FLASHING | SP TRACKING |
|-----------|----------------------|-------------|
| DEVIATION | ANNUNCIATOR FLASHING | SP TRACKING |
| DEVIATION | ANNUNCIATOR FLASHING | SP TRACKING |
| DEVIATION | ANNUNCIATOR FLASHING | SP TRACKING |
| DEVIATION | ANNUNCIATOR FLASHING | SP TRACKING |
| DEVIATION | ANNUNCIATOR FLASHING | SP TRACKING |

| SETPOINT FINAL SETTINGS | | | | | | | | | | |
|-------------------------|-----------|-----------|-----------|--|--|--|--|--|--|--|
| | 1st DIGIT | 2nd DIGIT | 3rd DIGIT | | | | | | | |
| SPC_1 | | | | | | | | | | |
| SPC_2 | | | | | | | | | | |
| SPC_3 | | | | | | | | | | |
| SPC_4 | | | | | | | | | | |
| SPC_5 | | | | | | | | | | |
| SPC_6 | | | | | | | | | | |

| PID CONTROL SETTINGS | | | | | | |
|----------------------|----|-----|-----|-----|-----|-------------|
| SPC_1 5 SPAN | PB | INT | DER | ARW | MCT | SP TRACKING |
| SPC_2 5 SPAN | PB | INT | DER | ARW | мст | SP TRACKING |
| SPC_3 5 SPAN | PB | INT | DER | ARW | МСТ | SP TRACKING |
| SPC_4 5 SPAN | PB | INT | DER | ARW | МСТ | SP TRACKING |
| SPC_5 5 SPAN | PB | INT | DER | ARW | MCT | SP TRACKING |
| SPC_65 SPAN | PB | INT | DER | ARW | МСТ | SP TRACKING |

| ı | TIMER MODE SETTIN | NGS | | | | | | | | | | |
|---|-------------------|--------|--------------------------------|-------|------------|------|-----------|--------------------------------|------------|-------|------------|-------|
| ı | SPC SETTING | NORMAL | NORMALLY OFF / PULSED ON MODES | | | | | NORMALLY ON / PULSED OFF MODES | | | | |
| | SFC SETTING | NORWAL | REPEA | T ON | PULSE | ON | 1-SHOT ON | 1-SHOT OFF | PULSE | OFF | REPEAT | OFF |
| _ | | | | | | | | | | | | |
| | SPC_16 | DOM | Resolution | OFF T | Resolution | DOM | DOM | M OFF | Resolution | OFF T | Resolution | OFF T |
| | | DOB | | ONT | | ON_T | M ON | DOB | | DOB | | ONT |
| | SPC_26 | DOM | Resolution | OFF T | Resolution | DOM | DOM | M OFF | Resolution | OFF T | Resolution | OFF T |
| | | DOB | | ONT | | ONT | M ON | DOB | | DOB | | ONT |
| | SPC_36 | DOM | Resolution | OFF T | Resolution | DOM | DOM | M OFF | Resolution | OFF T | Resolution | OFF T |
| | | DOB | | ONT | | ONT | M ON | DOB | | DOB | | ONT |
| | SPC_46 | DOM | Resolution | OFF T | Resolution | DOM | DOM | M OFF | Resolution | OFF T | Resolution | OFF T |
| | | DOB | | ONT | | ONT | M ON | DOB | | DOB | | ONT |
| | SPC_56 | DOM | Resolution | OFF T | Resolution | DOM | DOM | M OFF | Resolution | OFF T | Resolution | OFF T |
| | | DOB | | ONT | | ONT | M ON | DOB | | DOB | | ONT |
| | SPC_66 | DOM | Resolution | OFF T | Resolution | DOM | DOM | M OFF | Resolution | OFF T | Resolution | OFF T |
| | | DOB | | ONT | | ONT | M ON | DOB | | DOB | | ONT |

| REGISTER R | ESET & | TRIGGER | FUNCTIONS SETTINGS | | | | | | |
|------------|--------|---------|--------------------|--------|---------|---------|---------|-------|--|
| SPC_1 | 7 | [triG] | [dESt] | [ModE] | [rES_C] | [SourC] | [Print] | [LoG] | |
| SPC_2 | 7 | [triG] | [dESt] | [ModE] | [rES_C] | [SourC] | [Print] | [LoG] | |
| SPC_3 | 7 | [triG] | [dESt] | [ModE] | [rES_C] | [SourC] | [Print] | [LoG] | |
| SPC_4 | 7 | [triG] | [dESt] | [ModE] | [rES_C] | [SourC] | [Print] | [LoG] | |
| SPC_5 | 7 | [triG] | [dESt] | [ModE] | [rES_C] | [SourC] | [Print] | [LoG] | |
| SPC_6 | 7 | [triG] | [dESt] | [ModE] | [rES_C] | [SourC] | [Print] | [LoG] | |

Commonly Used Registers

Commonly Used Registers

Registers 1 to 244 can be used to select the source or reset destination in the following modes using the front panel buttons:

- Code 1 [X50]. Select data source for the primary display.
- Setpoint Control Settings [X1X]. Select data source for the selected setpoint.
- Setpoint Control Settings [XX7]. Select reset destination register for the selected setpoint.
- Setpoint Control Settings [XX7]. Select register to access source parameters to be copied to the reset destination register.

The table **Commonly Used Registers 1 to 244** lists the most commonly used registers available for front panel programming from register set 1 to 244. The list shows five columns where the register is commonly used as the source or reset destination in a function.

Where a register is commonly used as the source or reset destination, a double arrow ▶▶ is shown in the column. Where a register is not so commonly used, but could be used for this purpose, a single arrow ▶ is shown.

The first 11 registers shown in the table have no register number. This is because they are displayed in the select data source or reset destination modes using their register name and can be directly selected.

Registers That Should Not be Selected

The following registers are part of the 1 to 244 register set, but should not be selected for the reasons stated:

| 38 | Reserved for future developmen |
|---------|---------------------------------|
| 47-48 | Reserved for future development |
| 52-53 | Reserved for Texmate use only. |
| 61-64 | Reserved for future development |
| 123-128 | Reserved for future development |
| 140-141 | Reserved for future development |
| 234-244 | Reserved for future development |

| Commonly Used Registers 1 to 244 | | | | | | | | | | | | | |
|----------------------------------|--------|-----------------|-----------------|-----------------|-----------------|-----------------|---------------------------|----------|-------------|-------------|-------------|-----------------|-----------|
| Register Name Register Number | " | | | | Reset | Totalizer | Register Name | Register | | | | Reset | Totalizer |
| | Source | Source | Source | Destination | Source | Register Name | Number | Source | Source | Source | Destination | Source | |
| Display | - | | >> | | | >> | Variable 4 | 88 | > | > | > | > | |
| Result | - | >> | >> | >> | >> | >> | Variable 5 | 89 | > | > | > | > | |
| CH1 | - | >> | >> | >> | >> | >> | Variable 6 | 90 | > | > | > | > | |
| CH2 | - | >> | >> | >> | >> | >> | Variable 7 | 91 | > | > | > | > | |
| CH3 | - | >> | >> | >> | >> | >> | Variable 8 | 92 | > | > | > | > | |
| CH4 | - | >> | >> | >> | >> | >> | Variable 9 | 93 | > | > | > | > | |
| Total 1 | - | >> | >> | >> | >> | | Variable 10 | 94 | > | > | > | > | |
| Total 2 | - | >> | >> | >> | >> | | Timer 1 | 95 | > | > | > | > | |
| Peak | - | > | >> | > | >> | | Timer 2 | 96 | > | > | > | > | |
| Valley | - | > | >> | > | >> | | Smart Reset Offset 1 | 121 | | | | >> | |
| Tare | - | > | > | > | >> | | Smart Reset Offset 1 | 122 | | | | >> | |
| PID Output 1 | 50 | > | > | | | | Clock - Seconds | 213 | | > | | | |
| PID Output 2 | 51 | > | > | | | | Clock - Minutes | 214 | | > | | | |
| Smart Result 1 | 54 | | | | > | | Clock - Hours | 215 | | > | | | |
| Smart Result 2 | 55 | | | | > | | Clock – Days | 216 | | > | | | |
| Smart Result 3 | 56 | | | | > | | Clock - Date | 217 | | > | | | |
| Smart Result 4 | 57 | | | | > | | Clock - Month | 218 | | > | | | |
| Smart Result 5 | 58 | | | | > | | Clock - Year | 219 | | > | | | |
| Smart Result 6 | 59 | | | | > | | Setpoint Latch | 221 | | | | >> | |
| Smart Result 7 | 60 | | | | > | | Relay De-energize | 222 | | | | >> | |
| Analog Output 1 | 83 | > | > | > | > | | Auto Zero Offset – Result | 227 | | > | | | |
| Analog Output 2 | 84 | > | > | > | > | | Auto Zero Offset – CH1 | 228 | | > | | | |
| Variable 1 | 85 | > | > | > | > | | Auto Zero Offset – CH2 | 229 | | > | | | |
| Variable 2 | 86 | > | > | > | | | Auto Zero Offset – CH3 | 230 | | > | | | |
| Variable 3 | 87 | > | > | > | > | | Auto Zero Offset – CH4 | 231 | | > | | | |



Note:

3-digit programming codes are specified within square brackets [XXX]. If an X appears in the description of a 3-digit programming code or in a configuration procedure, this means that more than one choice can be made, or any number displayed in that digit is not relevant to the function being explained.

| Dreft Conv. Code Version V2 04e | Tiger 320 Series Programming Code Sheet |
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